

Finsler spacetimes, observer space and Cartan geometry

Manuel Hohmann

Laboratory of Theoretical Physics - Institute of Physics - University of Tartu
Center of Excellence "The Dark Side of the Universe"



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in your future

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Outline

1. Introduction

2. Geometries

2.1 Pseudo-Riemannian geometry

2.2 Finsler spacetime geometry

2.3 Observer space Cartan geometry

2.4 Relation between geometries

3. Application in physics

3.1 Causality

3.2 Observers

3.3 Gravity

4. Conclusion

Motivation

- Pseudo-Riemannian geometry of spacetime has multiple roles:
 - Causality
 - Observers, observables and observations
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- **Finsler spacetimes**
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- How to serve the same roles as pseudo-Riemannian geometry?

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- ? Possible explanations of yet unexplained phenomena:
 - ? Galaxy rotation curves
 - ? Accelerating expansion of the universe

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- Solution:
 - Consider space O of all allowed observers.
 - Describe experiments on observer space instead of spacetime.
 - ⇒ Observer dependence of physical quantities follows naturally.
 - ⇒ No preferred observers.
 - Geometry of observer space modeled by Cartan geometry.

Geometrical structures

Metric geometry

Manifold M

Lorentzian metric g

Orientation

Time orientation

Finsler geometry

Tangent bundle TM

Geometry function

$L : TM \rightarrow \mathbb{R}$

Finsler function

$F : TM \rightarrow \mathbb{R}$

Finsler metric $g^F(x, y)$

Cartan non-linear
connection N^a_b

Cartan linear
connection ∇

Cartan geometry

Lie group

$G = \text{ISO}_0(3, 1)$

Closed subgroup

$K = \text{SO}(3)$

Principal K -bundle

$\pi : P \rightarrow O$

Cartan connection

$A \in \Omega^1(P, \mathfrak{g})$

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From metric to Finsler

Coordinates (x^a) on M
Coordinates (x^a, y^a) on TM
Define $L(x, y) = g_{ab}(x)y^a y^b$

From Finsler to Cartan

Space O of observer 4-velocities
Space P of observer frames
Define A from connection ∇

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- Ingredients of pseudo-Riemannian spacetime geometry:
 - 4-dimensional spacetime manifold M .
 - Metric g_{ab} of Lorentzian signature $(-, +, +, +)$.
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- Clock postulate: proper time measured by arc length.

⇒ Arc length for curves $t \mapsto \gamma(t) \in M$ defined by the metric:

$$\tau_2 - \tau_1 = \int_{t_1}^{t_2} \sqrt{|g_{ab}(\gamma(t))\dot{\gamma}^a(t)\dot{\gamma}^b(t)|} dt.$$

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- Observables are components of tensor fields.
- Tensor components must be expressed in suitable basis.

⇒ Metric provides notion of orthonormal frames:

$$g_{ab}f_i^a f_j^b = \eta_{ij}.$$

⇒ Orthogonal frame bundle $\tilde{\pi} : P \rightarrow M$ is principal $SO(1, 3)$ -bundle.

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Basics of Finsler spacetimes

- Finsler geometry defined by length functional for curve γ :

$$\tau_2 - \tau_1 = \int_{t_1}^{t_2} F(\gamma(t), \dot{\gamma}(t)) dt$$

- Finsler function $F : TM \rightarrow \mathbb{R}^+$.
- Finsler geometries suitable for spacetimes exist. [C. Pfeifer, M. Wohlfarth '11]

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- Introduce manifold-induced coordinates (x^a, y^a) on TM :
 - Coordinates x^a on M .
 - Define coordinates y^a for $y^a \frac{\partial}{\partial x^a} \in T_x M$.
 - Tangent bundle TTM spanned by $\left\{ \partial_a = \frac{\partial}{\partial x^a}, \bar{\partial}_a = \frac{\partial}{\partial y^a} \right\}$.

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 - Tangent bundle TTM spanned by $\left\{ \partial_a = \frac{\partial}{\partial x^a}, \bar{\partial}_a = \frac{\partial}{\partial y^a} \right\}$.
 - n -homogeneous functions on TM : $f(x, \lambda y) = \lambda^n f(x, y)$.
 - n -homogeneous smooth geometry function $L : TM \rightarrow \mathbb{R}$.
 - ⇒ 1-homogeneous Finsler function $F = |L|^{\frac{1}{n}}$.
- ⇒ Finsler metric with Lorentz signature:

$$g_{ab}^F(x, y) = \frac{1}{2} \bar{\partial}_a \bar{\partial}_b F^2(x, y).$$

Connections on Finsler spacetimes

- Cartan non-linear connection:

$$N^a{}_b = \frac{1}{4} \bar{\partial}_b \left[g^{F ac} (y^d \partial_d \bar{\partial}_c F^2 - \partial_c F^2) \right].$$

- ⇒ Berwald basis of TTM :

$$\{\delta_a = \partial_a - N^b{}_a \bar{\partial}_b, \bar{\partial}_a\}.$$

- ⇒ Dual Berwald basis of T^*TM :

$$\{dx^a, \delta y^a = dy^a + N^a{}_b dx^b\}.$$

- ⇒ Splits $TTM = HTM \oplus VTM$ and $T^*TM = H^*TM \oplus V^*TM$.

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- Cartan linear connection:

$$\nabla_{\delta_a} \delta_b = F^c{}_{ab} \delta_c, \quad \nabla_{\delta_a} \bar{\partial}_b = F^c{}_{ab} \bar{\partial}_c, \quad \nabla_{\bar{\partial}_a} \delta_b = C^c{}_{ab} \delta_c, \quad \nabla_{\bar{\partial}_a} \bar{\partial}_b = C^c{}_{ab} \bar{\partial}_c,$$

$$F^c{}_{ab} = \frac{1}{2} g^F{}^{cd} (\delta_a g^F{}_{bd} + \delta_b g^F{}_{ad} - \delta_d g^F{}_{ab}),$$

$$C^c{}_{ab} = \frac{1}{2} g^F{}^{cd} (\bar{\partial}_a g^F{}_{bd} + \bar{\partial}_b g^F{}_{ad} - \bar{\partial}_d g^F{}_{ab}).$$

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 - G and H are Lie groups.
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- ⇒ Dimensions of Cartan and Klein geometry are related:
- **Dimension of the fibers: $\dim P - \dim M = \dim H$.**

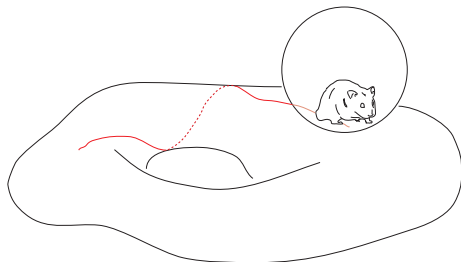
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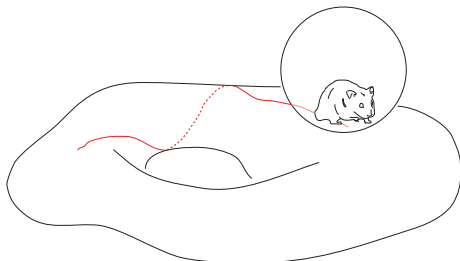
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 - ⇒ **Dimension of the base manifold:**
 $\dim M = \dim G - \dim H = \dim G/H$.

Toy model for Cartan geometry: The hamster ball



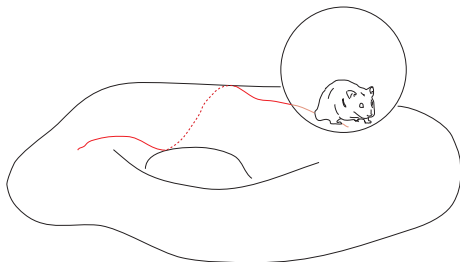
- Consider a hamster ball on a two-dimensional surface:
 - Two-dimensional Riemannian manifold (M, g) .
 - Orthonormal frame bundle $\pi : P \rightarrow M$ is principal $SO(2)$ -bundle.
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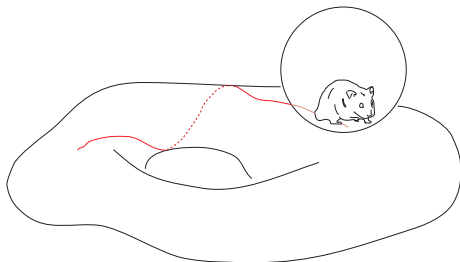
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 - "Rolling without slipping" over M .

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 - Rotations around its position $x = \pi(p)$: **subalgebra** $\mathfrak{h} = \mathfrak{so}(2)$.
 - "Rolling without slipping" over M : **quotient space** $\mathfrak{z} = \mathfrak{so}(3)/\mathfrak{so}(2)$.

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 - Rotations around its position $x = \pi(p)$: subalgebra $\mathfrak{h} = \mathfrak{so}(2)$.
 - "Rolling without slipping" over M : quotient space $\mathfrak{z} = \mathfrak{so}(3)/\mathfrak{so}(2)$.
- \Rightarrow Surface M "traced" by $S^2 \cong SO(3)/SO(2) = G/H$.
- \Rightarrow Geometry of M fully described by Hamster ball motion.

Klein geometries for spacetime and observer space

- Consider groups $G \supset H \supset K$:

- “Inhomogeneous group” - symmetry group of homogeneous space:

$$G_\Lambda = \begin{cases} \text{SO}_0(4, 1) & \Lambda = 1 \\ \text{ISO}_0(3, 1) & \Lambda = 0 \\ \text{SO}_0(3, 2) & \Lambda = -1 \end{cases} .$$

- “Homogeneous group” $H = \text{SO}_0(3, 1)$ - stabilizer of a point.
- “Observer group” $K = \text{SO}(3)$ - stabilizer of a tangent vector.

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- Induced split of Lie algebra \mathfrak{g} via Ad:
 - Irreducible representations of $H \subset G$ on \mathfrak{g} :

$$\mathfrak{g} = \underbrace{\mathfrak{h}}_{\text{Lorentz transformations}} \oplus \underbrace{\mathfrak{z}}_{\text{translations}} .$$

- Irreducible representations of $K \subset G$ on \mathfrak{g} :

$$\mathfrak{h} = \underbrace{\mathfrak{k}}_{\text{rotations}} \oplus \underbrace{\mathfrak{h}}_{\text{boosts}} , \quad \mathfrak{z} = \underbrace{\vec{\mathfrak{z}}}_{\text{spatial translations}} \oplus \underbrace{\mathfrak{z}^0}_{\text{temporal translations}} .$$

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- Consider Lorentzian manifold (M, g) .
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$$T_p P = V_p P + H_p P$$

- Infinitesimal Lorentz transforms $\in V_p P$.
- Infinitesimal translations $\in H_p P$.

Cartan geometry of spacetime

- Consider Lorentzian manifold (M, g) .
- Orthonormal frame bundle $\tilde{\pi} : P \rightarrow M$ is principal H -bundle.
- Split of the tangent spaces $T_p P \cong \mathfrak{g}$:

$$\begin{array}{ccccc} T_p P & = & V_p P & + & H_p P \\ \downarrow & & \downarrow & & \downarrow \\ \mathfrak{g} & = & \mathfrak{h} & + & \mathfrak{z} \end{array}$$

- Infinitesimal Lorentz transforms $\in V_p P \cong \mathfrak{h}$.
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- Corresponding split of Poincaré algebra \mathfrak{g} :
 - Lorentz algebra \mathfrak{h} .
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- *Cartan connection* $A = \omega + e \in \Omega^1(P, \mathfrak{g})$.

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- *Cartan connection* $A = \omega + \mathbf{e} \in \Omega^1(P, \mathfrak{g})$.
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Cartan geometry of spacetime

- Consider Lorentzian manifold (M, g) .
- Orthonormal frame bundle $\tilde{\pi} : P \rightarrow M$ is principal H -bundle.
- Split of the tangent spaces $T_p P \cong \mathfrak{g}$:

$$\begin{array}{ccccc} T_p P & = & V_p P & + & H_p P \\ \uparrow \scriptstyle A_p & & \uparrow & & \uparrow \\ \mathfrak{g} & = & \mathfrak{h} & + & \mathfrak{z} \end{array}$$

- Infinitesimal Lorentz transforms $\in V_p P \cong \mathfrak{h}$.
 - Infinitesimal translations $\in H_p P \cong \mathfrak{z}$.
 - Corresponding split of Poincaré algebra \mathfrak{g} :
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- Infinitesimal rotations $\in R_p P \cong \mathfrak{k}$.
- Infinitesimal Lorentz boosts $\in B_p P \cong \mathfrak{h}$.
- Infinitesimal spatial translations $\in \vec{H}_p P \cong \vec{\mathfrak{z}}$.
- Infinitesimal temporal translations $\in H_p^0 P \cong \mathfrak{z}^0$.

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2.1 Pseudo-Riemannian geometry

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From pseudo-Riemannian to Finsler

- Metric-induced 2-homogeneous geometry function:

$$L(x, y) = g_{ab}(x)y^a y^b.$$

⇒ Finsler function $F(x, y) = \sqrt{|L(x, y)|}$.

⇒ Finsler metric

$$g^F(x, y) = \begin{cases} -g(x, y) & \text{for } y \text{ timelike,} \\ g(x, y) & \text{for } y \text{ spacelike.} \end{cases}$$

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⇒ Cartan non-linear connection:

$$N^a_b = \Gamma^a_{bc} y^c.$$

⇒ Cartan linear connection:

$$F^a_{bc} = \Gamma^a_{bc}, \quad C^a_{bc} = 0.$$

From Finsler to Cartan

- Need to construct $A \in \Omega^1(P, \mathfrak{g})$.
- Recall that

$$\begin{aligned}\mathfrak{g} &= \mathfrak{h} \oplus \mathfrak{z} \\ A &= \omega + e\end{aligned}$$

- Definition of e : Use the *solder form*:

$$e^i = f^{-1i}{}_a dx^a.$$

- Definition of ω : Use the *Cartan linear connection*:

$$\omega^i{}_j = f^{-1i}{}_a \left[df_j^a + f_j^b \left(dx^c F^a{}_{bc} + (dx^d N^c{}_d + df_0^c) C^a{}_{bc} \right) \right].$$

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- Let $a = z^i \mathcal{Z}_i + \frac{1}{2} h^i{}_j \mathcal{H}_i^j \in \mathfrak{g}$.
- Fundamental vector fields:

$$\underline{A}(a) = z^i f_i^a \left(\partial_a - f_j^b F^c{}_{ab} \bar{\partial}_c^j \right) + \left(h^i{}_j f_i^a - h^i{}_0 f_i^b f_j^c C^a{}_{bc} \right) \bar{\partial}_a^j.$$

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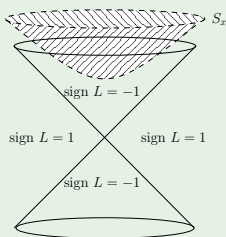
Causal structure

Metric geometry

Geometry function:

$$L = g_{ab}y^a y^b$$

y^a timelike for $L < 0$.



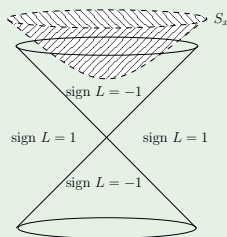
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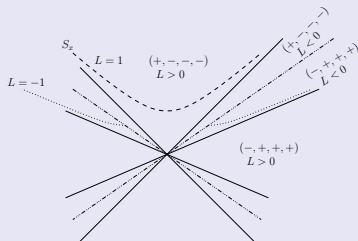
Finsler geometry

Fundamental geometry function L

Hessian:

$$g_{ab}^L(x, y) = \frac{1}{2} \bar{\partial}_a \bar{\partial}_b L(x, y)$$

Use sign of L and signature of g^L .



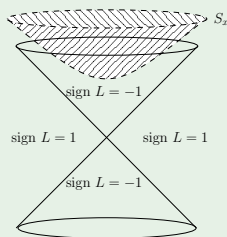
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Cartan geometry

Observer space:

$$O = \bigcup_{x \in M} S_x$$

O contains only future unit timelike vectors.

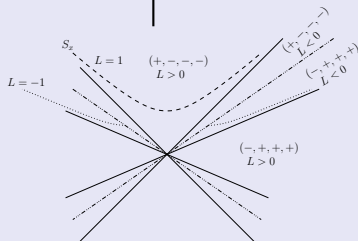
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Causality of Finsler spacetimes

- “Unit timelike condition” required for Finsler spacetimes:

For all $x \in M$ the set

$$\Omega_x = \{y \in T_x M \mid |L(x, y)| = 1, \text{sig } \bar{\partial}_a \bar{\partial}_b L(x, y) = (\epsilon, -\epsilon, -\epsilon, -\epsilon)\}$$

with $\epsilon = L(x, y)/|L(x, y)|$ contains a non-empty closed connected component $S_x \subseteq \Omega_x \subset T_x M$.

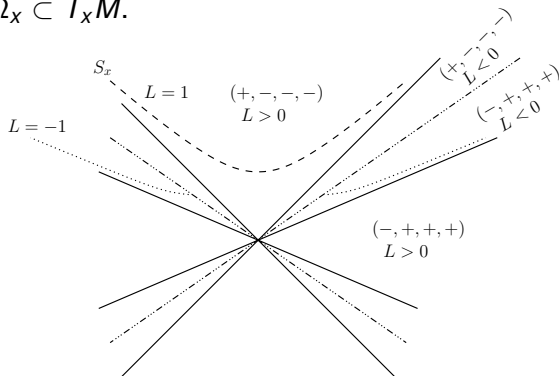
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with $\epsilon = L(x, y)/|L(x, y)|$ contains a non-empty closed connected component $S_x \subseteq \Omega_x \subset T_x M$.

- $\Rightarrow S_x$ contains physical observers.
- $\Rightarrow \mathbb{R}^+ S_x$ is convex cone.



The observer frame bundle

- Observer space of a Finsler spacetime:
 - Consider all allowed observer tangent vectors:

$$O = \bigcup_{x \in M} S_x.$$

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- Construct orthonormal observer frames:
 - ⇒ Complete $y = f_0$ to a frame f_i with $g_{ab}^F(x, y)f_i^a f_j^b = -\eta_{ij}$.
 - Let P be the space of all observer frames.
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 - Let P be the space of all observer frames.
 - Natural projection $\pi : P \rightarrow O$ discards spatial frame components.
- Group action on the frame bundle:
 - $SO(3)$ acts on spatial frame components by rotations.
 - Action is free and transitive on fibers of $\pi : P \rightarrow O$.
 - $\Rightarrow \pi : P \rightarrow O$ is principal K -bundle.

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Metric geometry

Timelike curve γ :

$$\begin{aligned}\gamma &: \mathbb{R} \rightarrow M \\ \tau &\mapsto \gamma(\tau)\end{aligned}$$

$$g_{ab}\dot{\gamma}^a\dot{\gamma}^b = -1$$

Orthonormal frame f :

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$$\dot{\gamma}(\tau) \in \mathcal{S}_{\gamma(\tau)} \subset TM$$

Canonical lift Γ :

$$\Gamma(\tau) = (\gamma(\tau), \dot{\gamma}(\tau))$$

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Cartan geometry

Observer curve Γ :

$$\begin{aligned}\Gamma &: \mathbb{R} \rightarrow \mathcal{O} \\ \tau &\mapsto \Gamma(\tau)\end{aligned}$$

Lift condition:

$$\tilde{e}^i \dot{\Gamma}(\tau) = \delta_0^i$$

Orthonormal frame f :

$$f \in \pi^{-1}(\Gamma(\tau)) \subset P$$

Metric geometry

Minimize arc length integral:

$$\int_{t_1}^{t_2} \sqrt{|g_{ab}(\gamma(t))\dot{\gamma}^a(t)\dot{\gamma}^b(t)|} dt$$

Geodesic equation:

$$\ddot{\gamma}^a + \Gamma^a_{bc}\dot{\gamma}^b\dot{\gamma}^c = 0$$

Inertial observers

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Finsler geometry

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$$\int_{t_1}^{t_2} F(\gamma(t), \dot{\gamma}(t)) dt$$

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Geodesic spray:

$$\mathbf{S} = y^a(\partial_a - N^b_a \bar{\partial}_b)$$

Integral curves:

$$\dot{\Gamma}(\tau) = \mathbf{S}(\Gamma(\tau))$$

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 - Observer trajectory γ in M .
 - $\dot{\gamma}$ must be timelike and future-directed.

Observers on metric spacetimes

- Observer trajectories:
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 - $\dot{\gamma}$ must be timelike and future-directed.
- Inertial observers:
 - Minimize arc-length functional:

$$\int_{t_1}^{t_2} \sqrt{|g_{ab}(\gamma(t))\dot{\gamma}^a(t)\dot{\gamma}^b(t)|} dt.$$

⇒ Geodesic equation:

$$\ddot{\gamma}^a + \Gamma^a_{bc}\dot{\gamma}^b\dot{\gamma}^c = 0.$$

Observers on Finsler spacetimes

- Observer trajectories and canonical lifts:
 - Observer trajectory γ in M .
 - Lift γ to a curve $\Gamma = (\gamma, \dot{\gamma})$ in TM .
 - Curves Γ in TM are canonical lifts if and only if

$$\dot{\Gamma} \lrcorner dx^a = y^a.$$

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⇒ Geodesic equation:

$$\ddot{\gamma}^a + N^a_b \dot{\gamma}^b = 0.$$

⇒ Γ is integral curve of geodesic spray:

$$\dot{\Gamma} = \mathbf{S} = y^a \delta_a.$$

Observers on Cartan observer space

- Observer curves:
 - Consider curve Γ in O .
 - \Rightarrow Tangent vector splits into translation and boost:

$$\dot{\Gamma} = \left(e^j \dot{\Gamma} \right) \underline{e}_j + \left(b^\alpha \dot{\Gamma} \right) \underline{b}_\alpha .$$

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- Translational component of the tangent vector:
 - Split into time and space components:

$$\left(e^j \dot{\Gamma} \right) \underline{e}_j = \left(e^0 \dot{\Gamma} \right) \underline{e}_0 + \left(e^\alpha \dot{\Gamma} \right) \underline{e}_\alpha .$$

- Components are relative to observer's frame.
- ⇒ Physical observer: translation corresponds to time direction:

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- Boost component of the tangent vector:
 - Measures acceleration in observer's frame.
 - Inertial observers are non-accelerating: $b^\alpha \dot{\Gamma} = 0$.
 - ⇒ Inertial observers follow integral curves of time translation: $\dot{\Gamma} = \underline{e}_0$.

- Generating vector field on Finsler spacetimes:
 - Geodesic spray \mathbf{S} preserves Finsler function: $\mathbf{S}F = 0$.
 - \Rightarrow Geodesic spray \mathbf{S} is tangent to observer space O (level set).
 - \rightsquigarrow Define Reeb vector field $\mathbf{r} = \mathbf{S}|_O$.
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- Temporal frame component is observer velocity: $f_0^a = y^a$.

Observers from Finsler to Cartan

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- Relation between connections coefficients: $y^a F^c{}_{ab} = N^c{}_b$.

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 - Relation between connections coefficients: $y^a F^c{}_{ab} = N^c{}_b$.
- \Rightarrow Observer trajectories Γ agree in Finsler and Cartan descriptions.
- \Rightarrow Cartan trajectories correspond to Finslerian parallel transport.

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Einstein-Hilbert action:

$$S_{\text{EH}} = \frac{1}{2\kappa} \int_M d^4x \sqrt{-g} R$$

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Einstein-Hilbert action:

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Using horizontal vector fields:

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Gravity from Cartan to Finsler

- MacDowell-Mansouri gravity on observer space: [S. Gielen, D. Wise '12]

$$S_G = \int_O \epsilon_{\alpha\beta\gamma} \operatorname{tr}_{\mathfrak{h}}(F_{\mathfrak{h}} \wedge \star F_{\mathfrak{h}}) \wedge b^\alpha \wedge b^\beta \wedge b^\gamma$$

- Hodge operator \star on \mathfrak{h} .
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- Translate terms into Finsler language (with $R = d\omega + \frac{1}{2}[\omega, \omega]$):

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- Cosmological constant:

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- Gauss-Bonnet term:

$$R \wedge \star R \rightsquigarrow \epsilon^{abcd} \epsilon^{efgh} R_{abef} R_{cdgh} dV.$$

⇒ Gravity theory on Finsler spacetime.

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⇒ Gravity theory on observer space.

Outline

1. Introduction

2. Geometries

2.1 Pseudo-Riemannian geometry

2.2 Finsler spacetime geometry

2.3 Observer space Cartan geometry

2.4 Relation between geometries

3. Application in physics

3.1 Causality

3.2 Observers

3.3 Gravity

4. Conclusion

Summary

- Finsler spacetimes
 - Generalization of pseudo-Riemannian spacetimes.
 - Geometry defined by function L on TM .
 - Lengths measured by Finsler function $F = |L|^{\frac{1}{n}}$.
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- Different geometries provide compatible definitions of:
 - Causality
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 - Observables
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Caveats and outlook

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 - Lagrangian defined on jet bundle over configuration bundle.
 - Critical sections: solutions of Euler-Lagrange equations.
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