

Automatically introducing templates in Domain-Specific Languages

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Outline

- **Basics**
 - What is a template?
 - How is a language described?
 - How to plug templates in?
 - Intermediate summary
- **Some notes on correctness**
 - Issues with names
 - Constraints for name resolution
 - Open issues
- **Conclusion**

MyToy Language

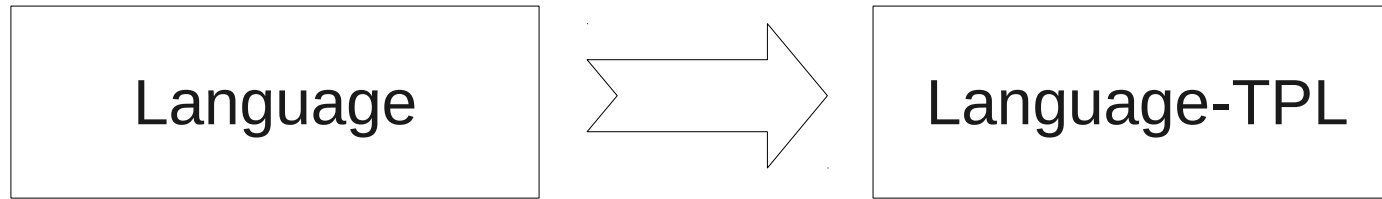
```
VAR x = 2; VAR y = 5;
VAR xy = 0;
VAR trigger = 0;
COMEFROM trigger = 1;
  xy = xy + y;
  x = x - 1;
  trigger = 1;
COMEFROM x = 0;
```

```
VAR x = 2; VAR y = 5;
VAR xy = 0;
$UNTIL <x = 0> <
  xy = xy + y;
  x = x - 1;
>;
```

MyToy-TPL
Language

```
template $UNTIL <condition> <body> {
  VAR trigger = 0;
  comefrom trigger = 1;
  <body>
  trigger = 1;
  comefrom <condition>;
}
```

Our Goal

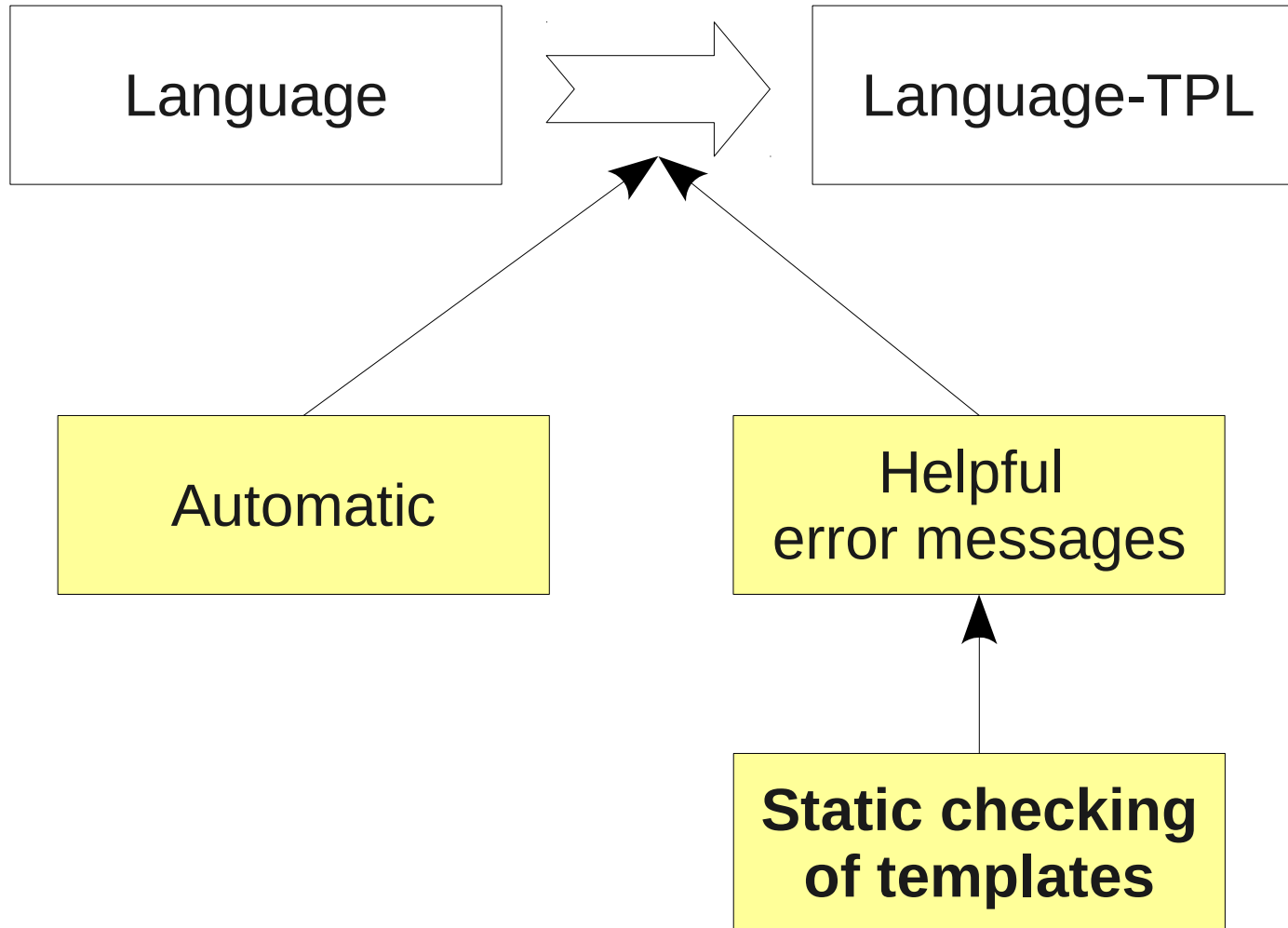


- C preprocessor (cpp)
- C++ templates
- Lisp
- Nemerle macros
- **NOT** Java Generics

Useless error messages

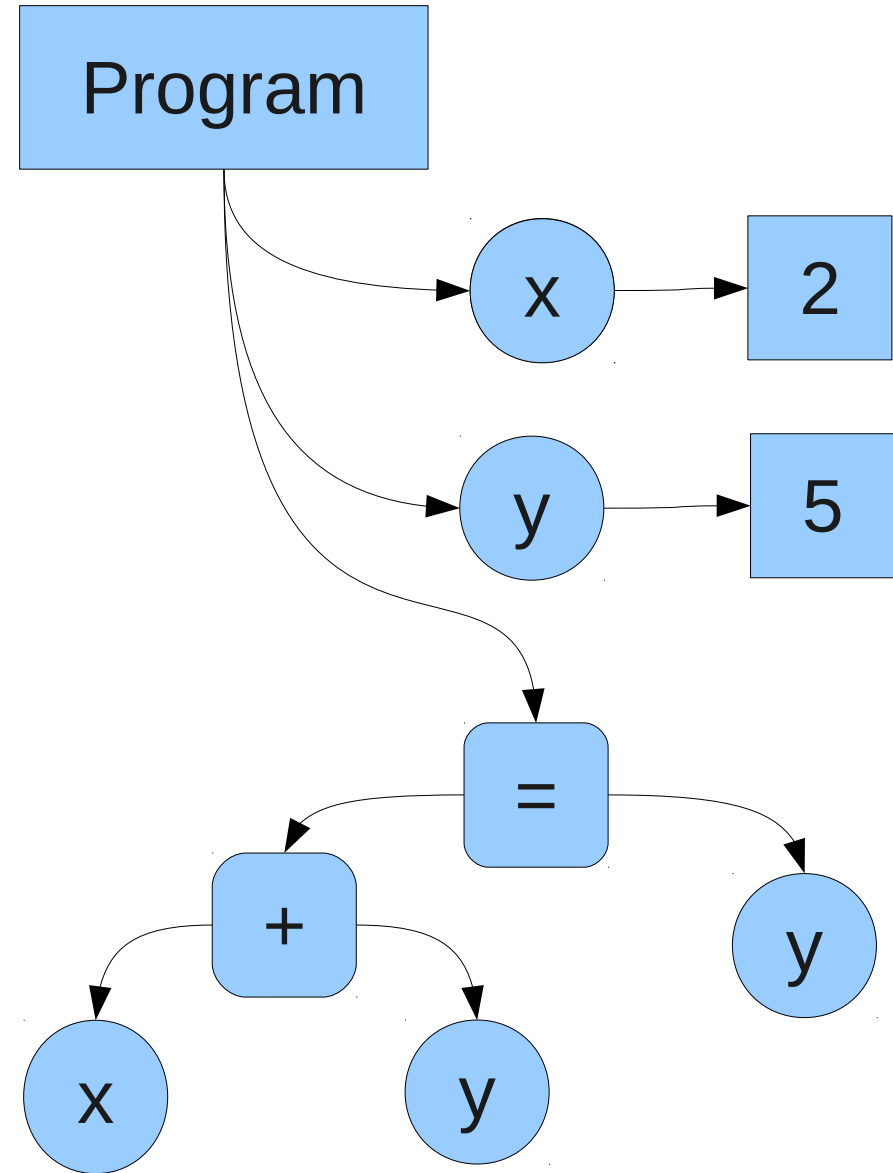
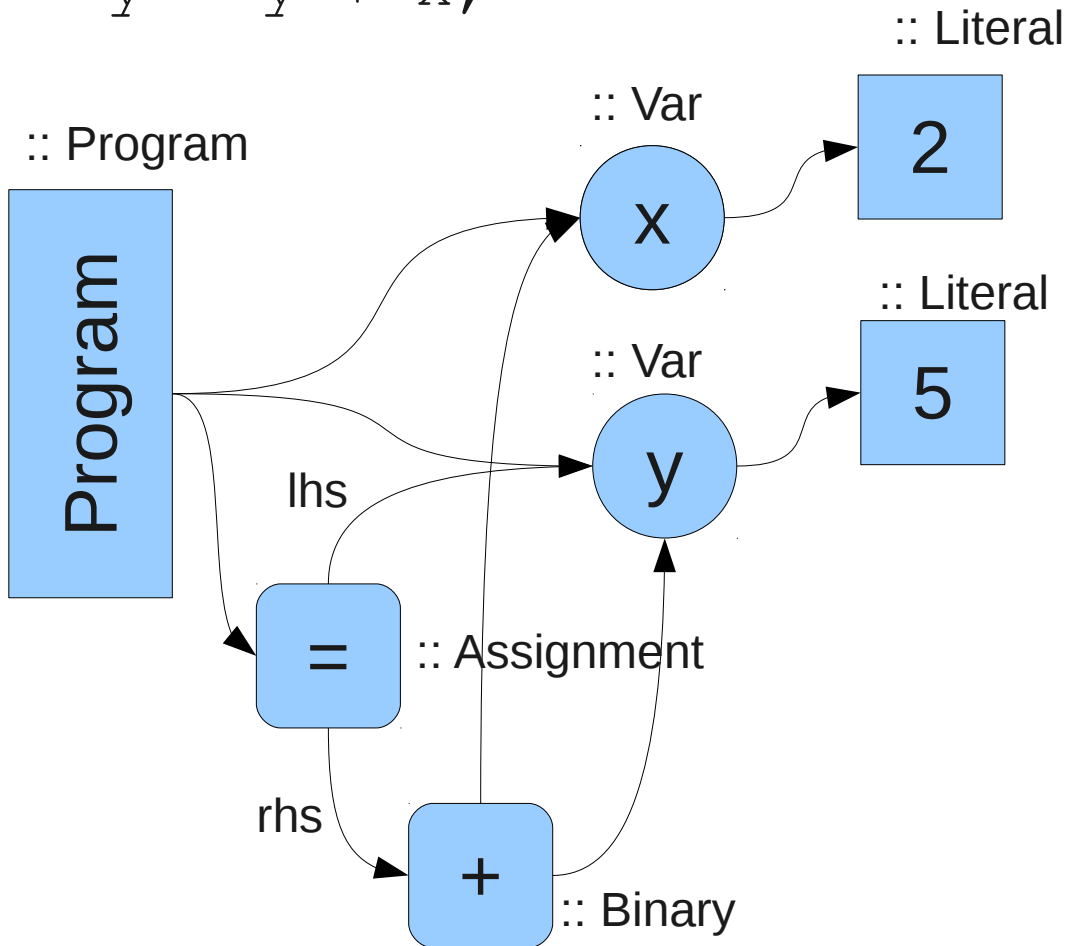
Only one language

Our Goal

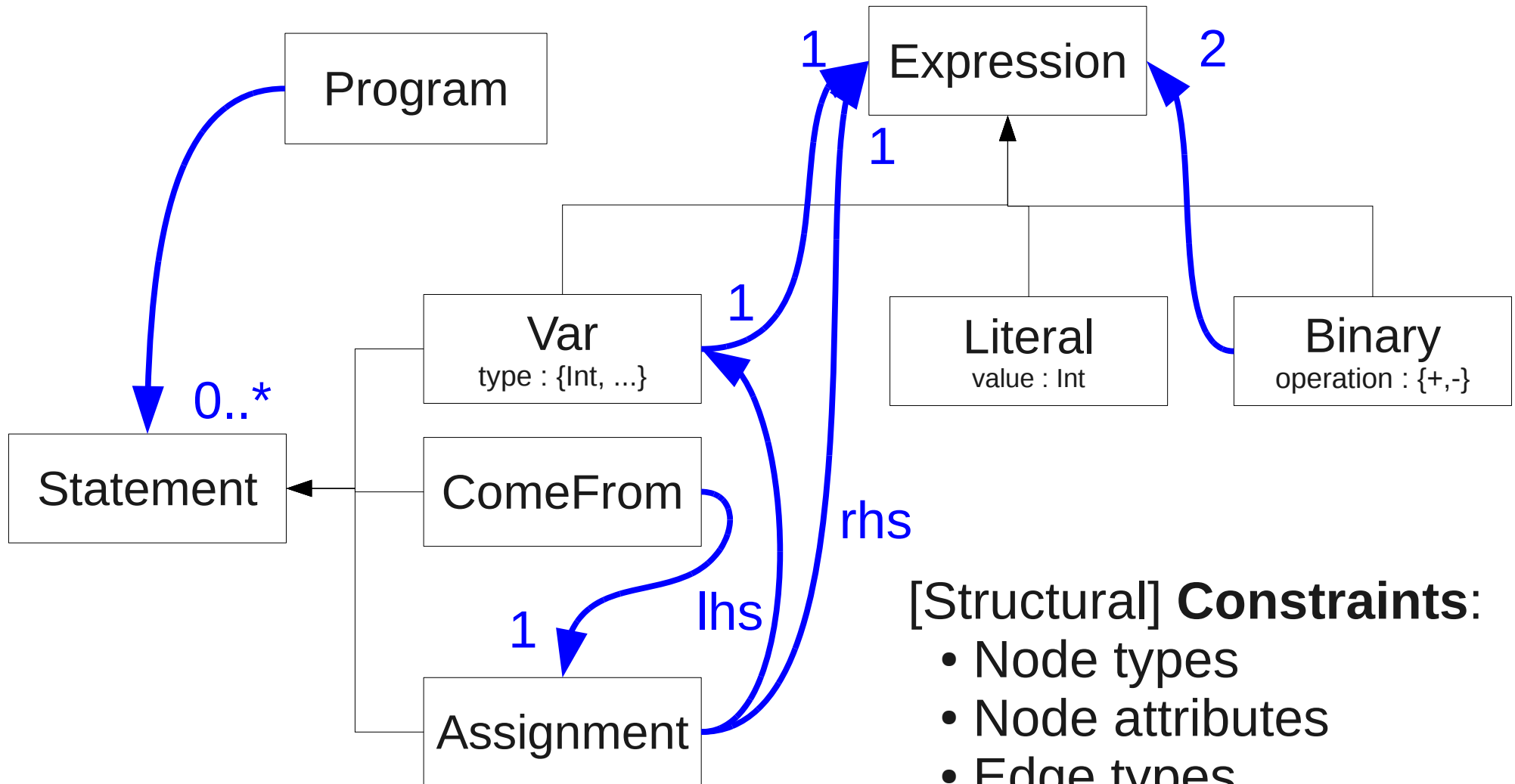


Alternative Views of a Program

```
VAR x = 2;  
VAR y = 5;  
y = y + x;
```



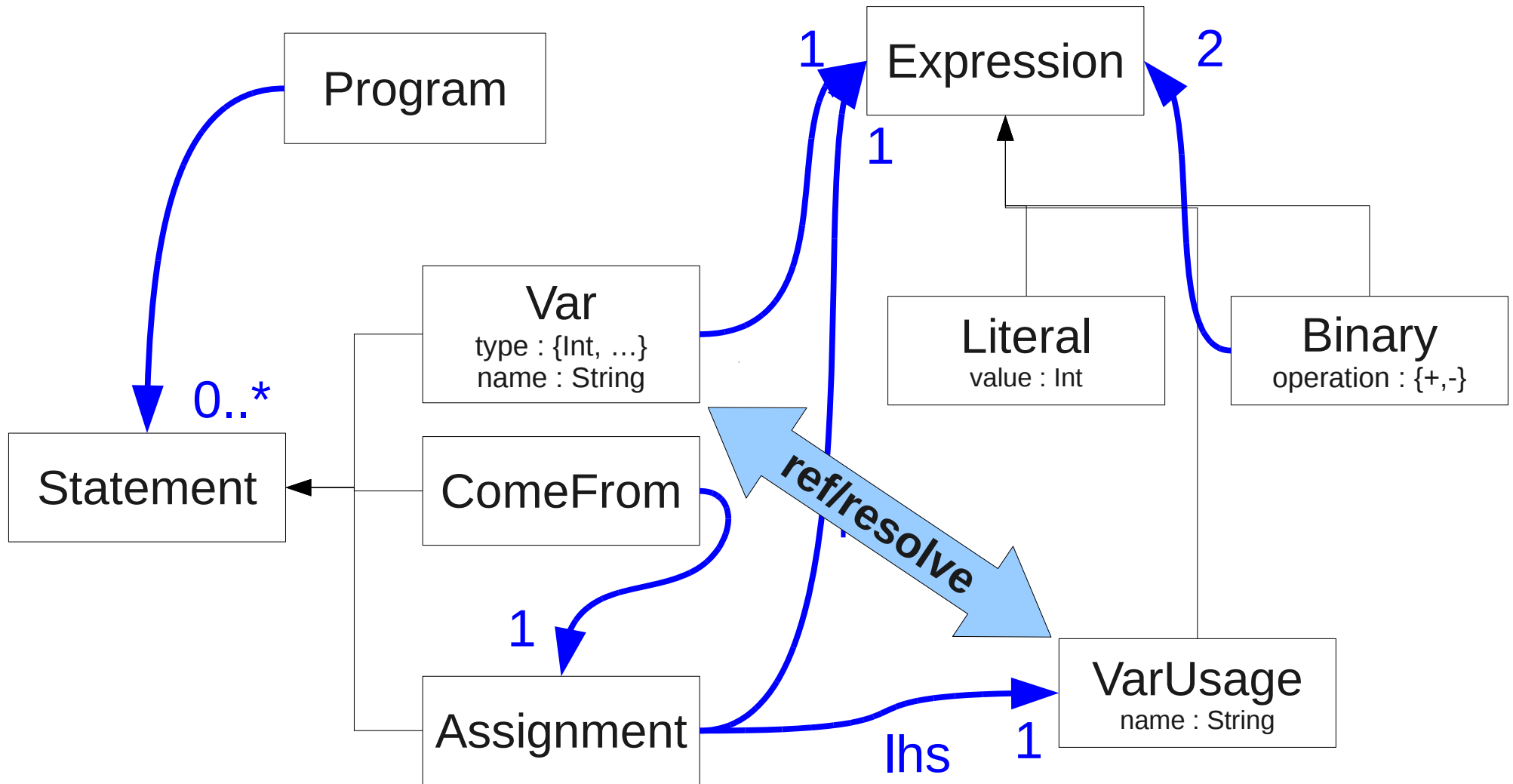
Describing graph structure



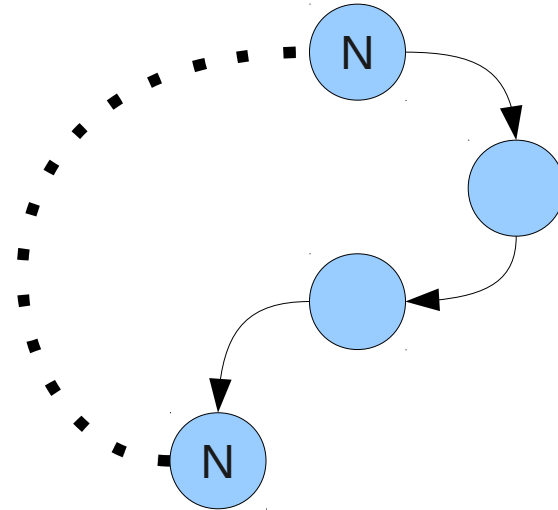
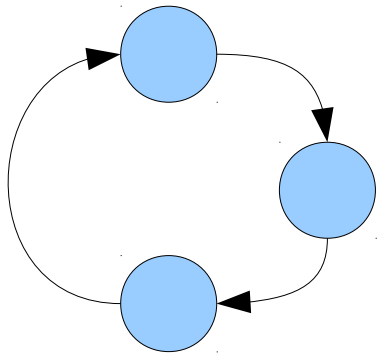
[Structural] Constraints:

- Node types
- Node attributes
- Edge types
- Edge multiplicities
- Typing of edge ends

Describing tree structure



Templates for Graph



Graph

AST

Serialize

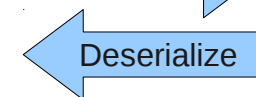
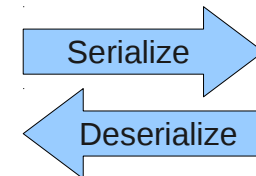
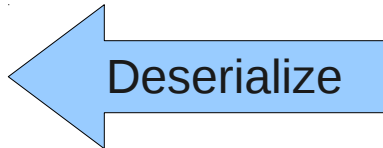
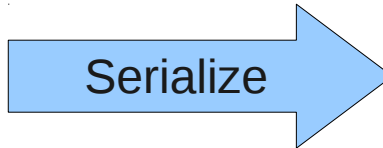
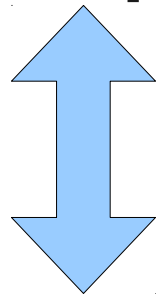
Deserialize

Templates

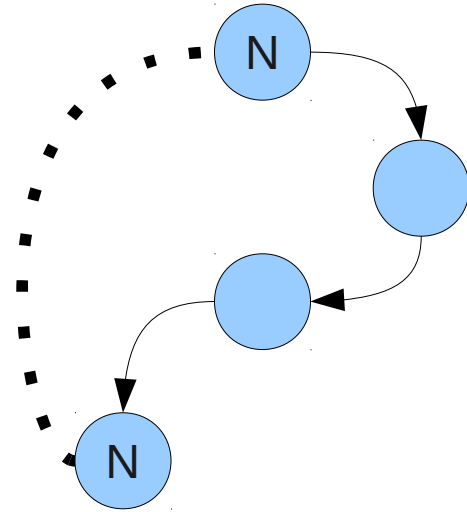
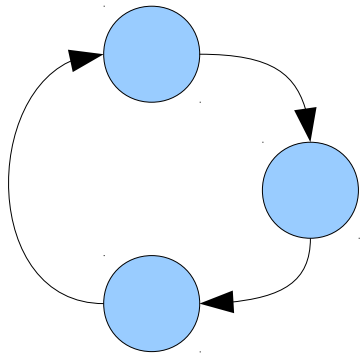
Templates AST

Serialize

Deserialize



Templates for AST



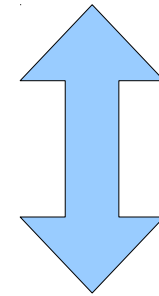
Graph

Serialize

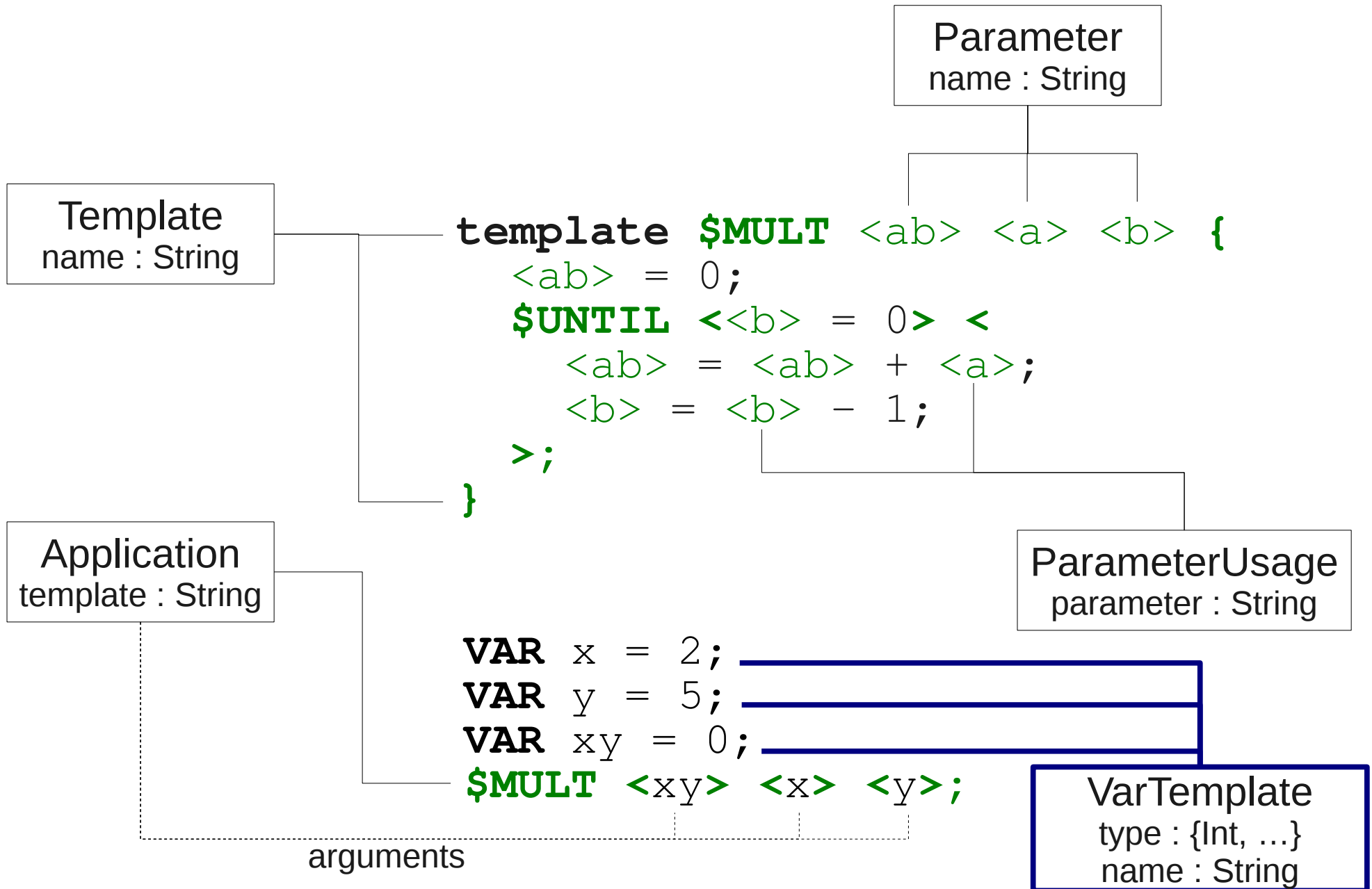
Deserialize

AST

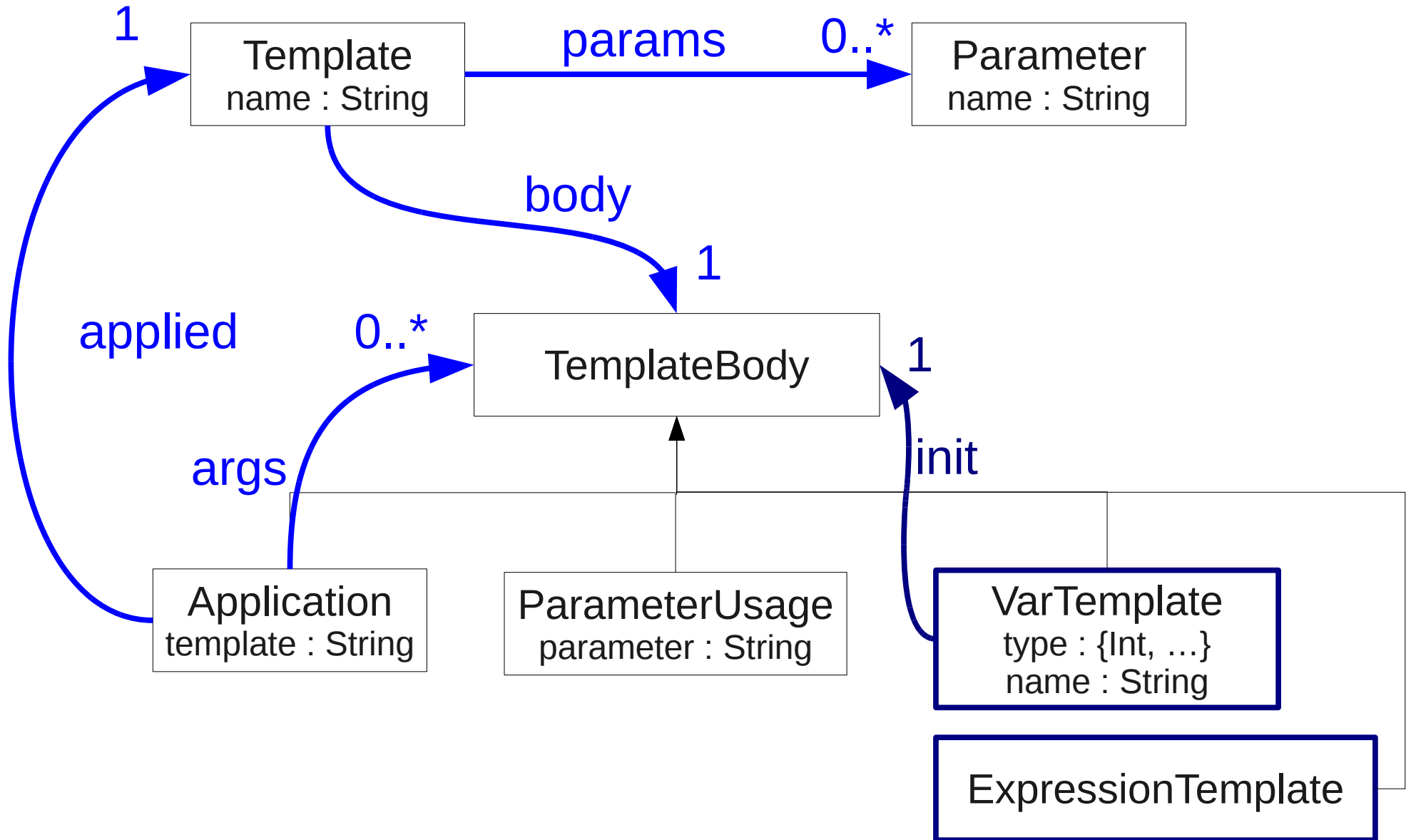
Templates AST



Describing templates

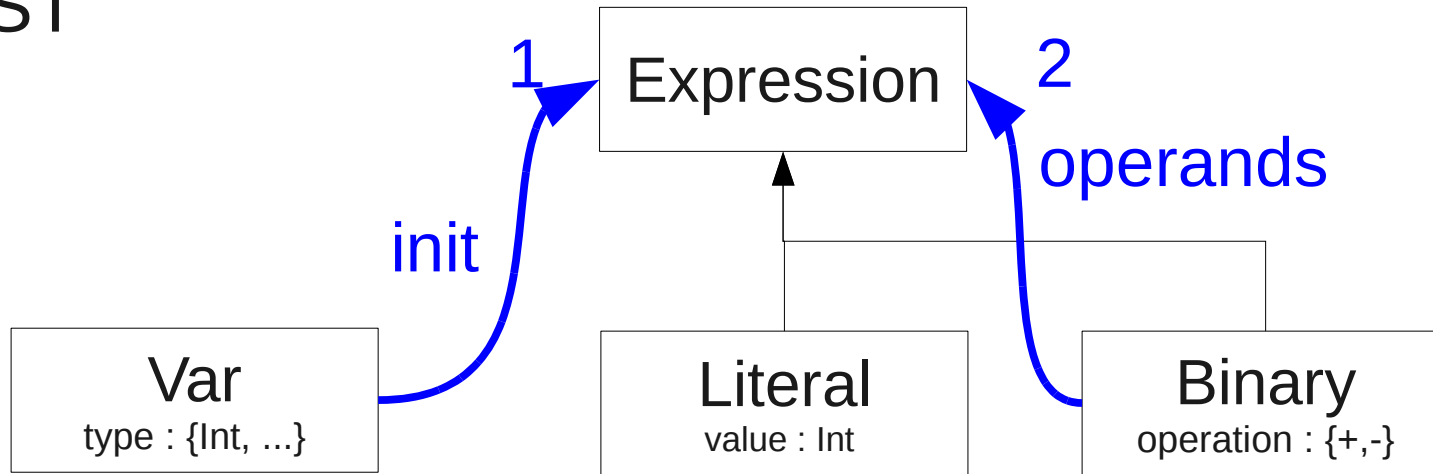


Template Description

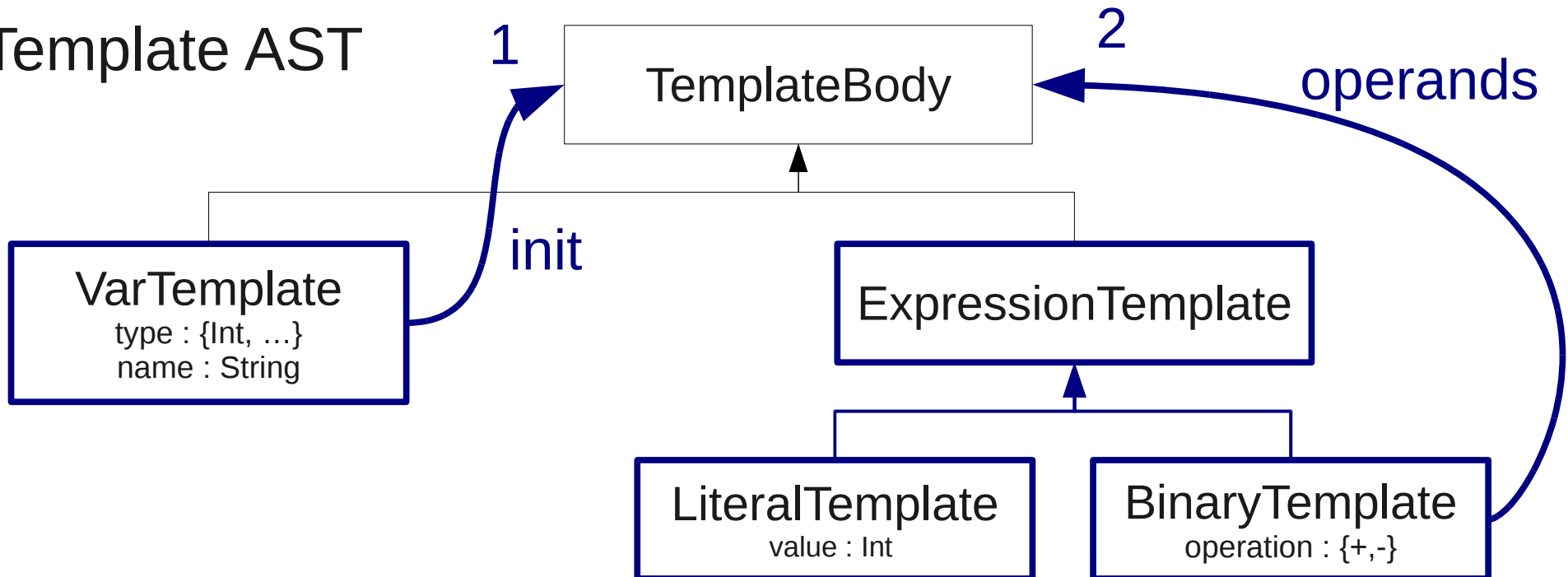


Language-Specific Templates

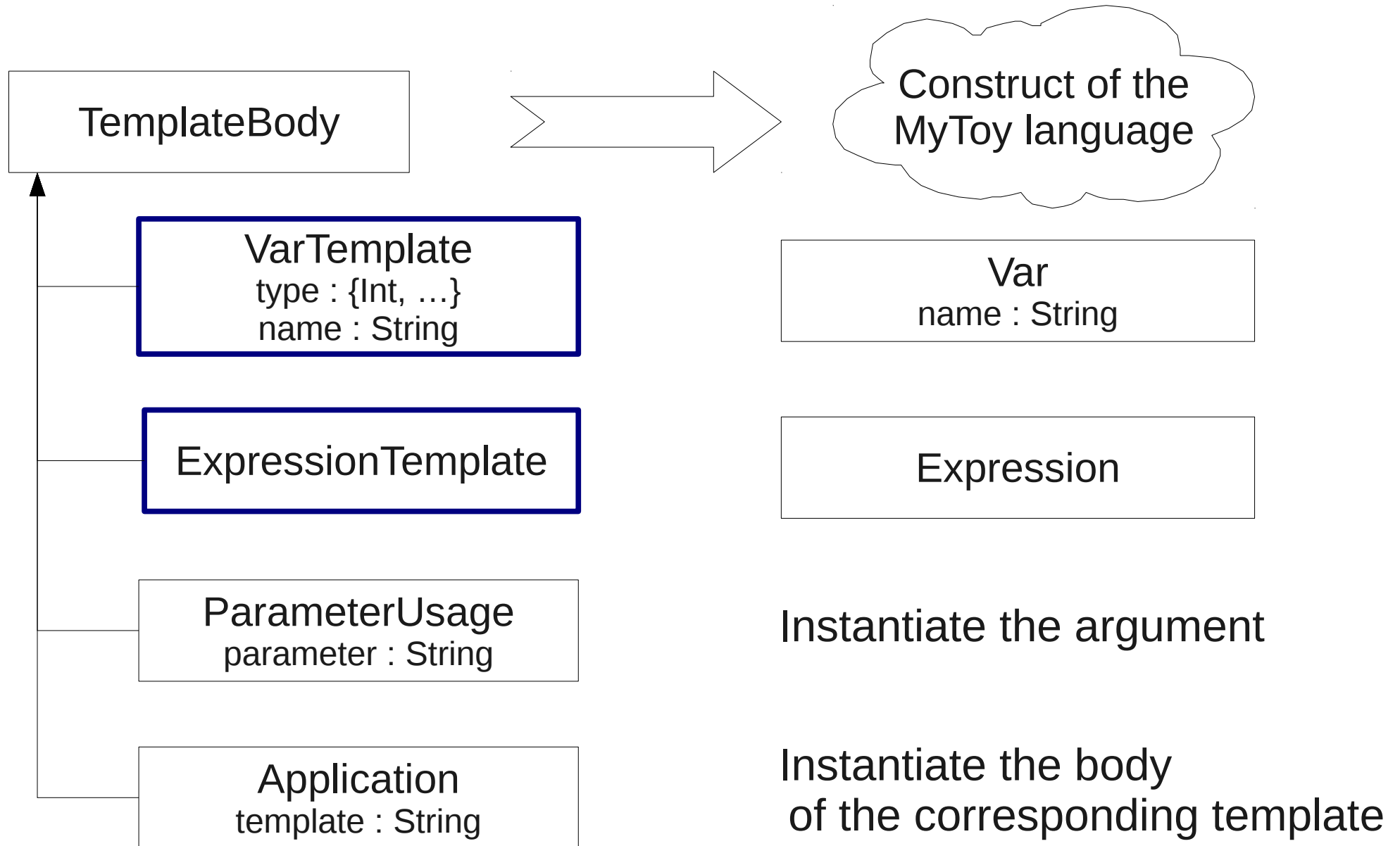
Initial AST



Template AST



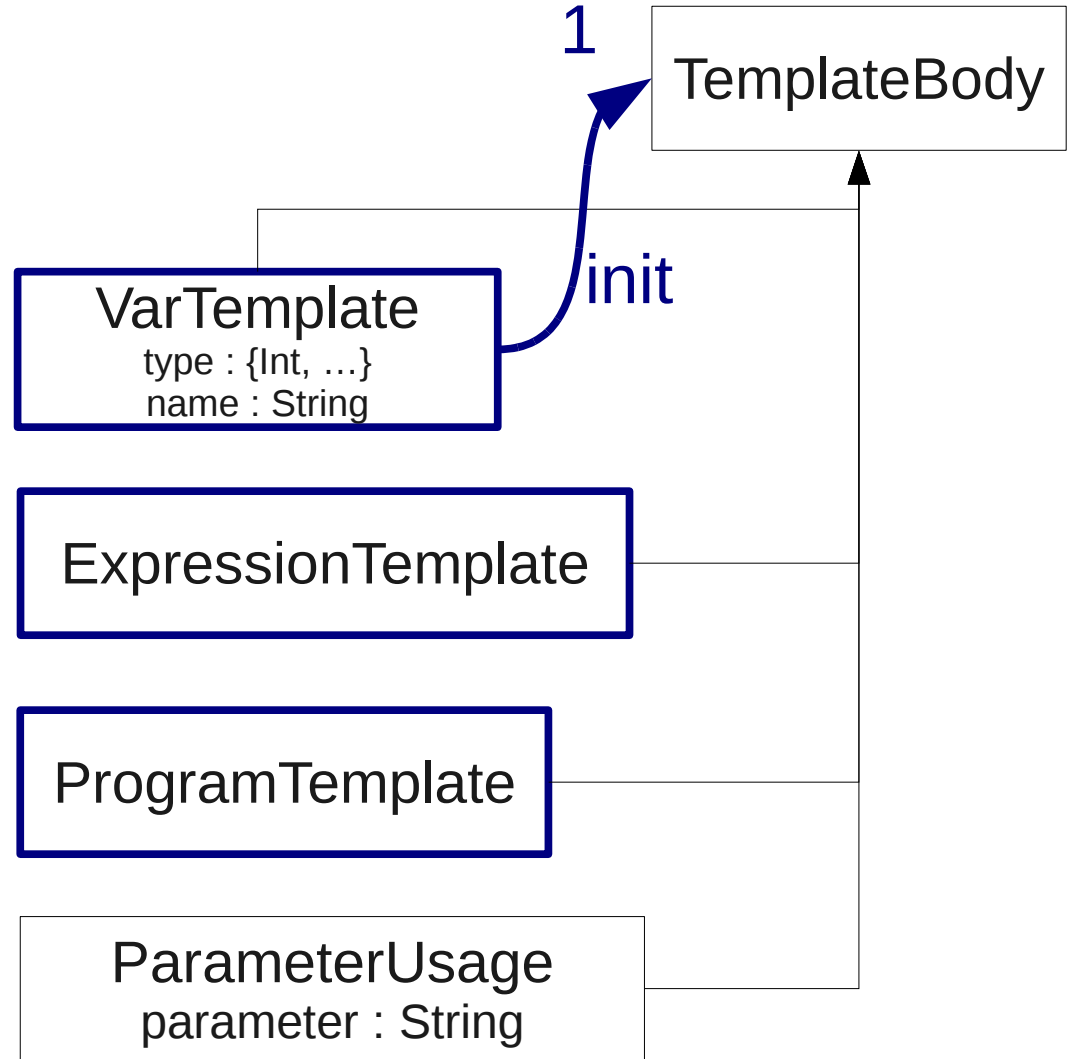
Instantiation



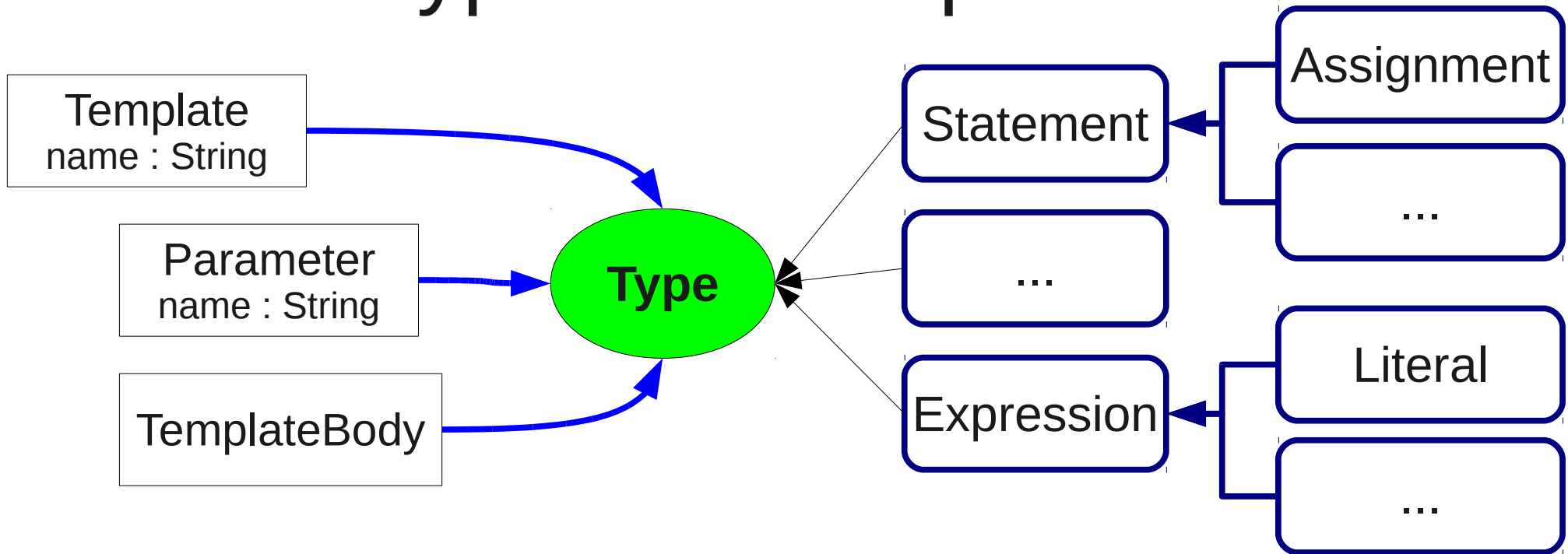
Structural Correctness

Constraints:

- Node types
- Node attributes
- Edge types
- Edge multiplicities
- **Typing of edge ends**



Types for Templates



```
template $UNTIL :: Statement[1..*]  
  <condition :: Assignment[1]>  
  <body :: Statement[0..*]> {  
    VAR trigger = 0 :: Literal[1];  
    comefrom trigger = 1;  
    <body>  
    Trigger = 1; :: Assignment[1]  
    comefrom <condition>;  
  }
```

Types
reflect
multiplicities

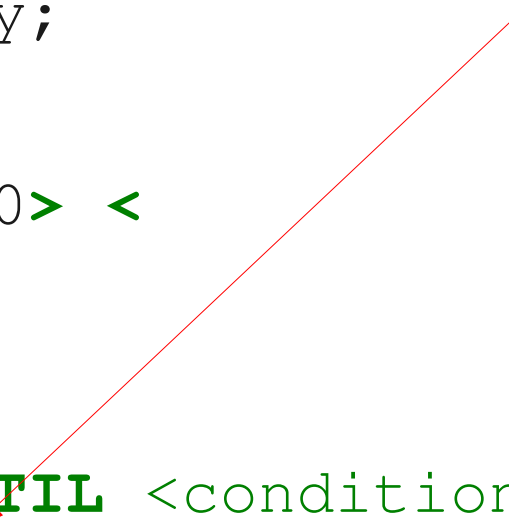
Intermediate Summary

- A language is described as (Graph \leftrightarrow AST)
- We extend a language to support templates
- We generate a type checker for templates
 - (no type annotations required)
 - This facilitates error reporting
- We generate an instantiation procedure
- Everything else is reused from the original language
- That's all great, but we capture only **some** errors

One more type of errors

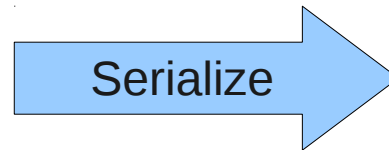
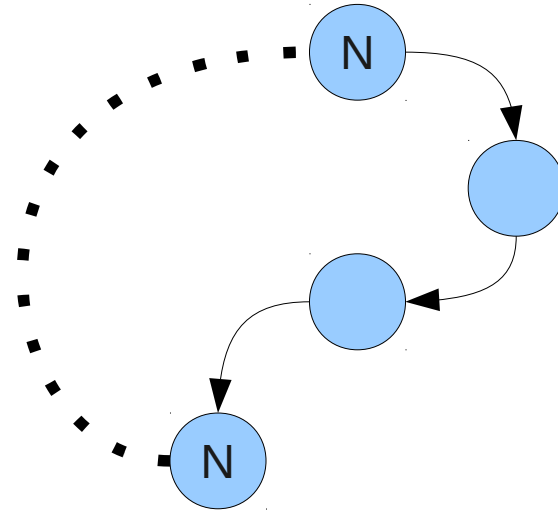
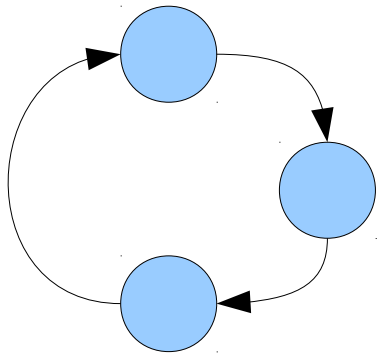
```
VAR x = 2; VAR y = 5;
VAR xy = 0;
$UNTIL <x = 0> <
  xy = xy + y;
  x = x - 1;
>;
$UNTIL <y = 0> <
  y = y - 1;
>;
```

**Error: variable
'trigger' is already
defined!**



```
template $UNTIL <condition> <body> {
  VAR trigger = 0;
  comefrom trigger = 1;
  <body>
  trigger = 1;
  comefrom <condition>;
}
```

Who said that was an error?!



Graph

AST

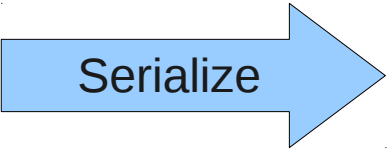
Structural
Constraints

Identification
Constraints

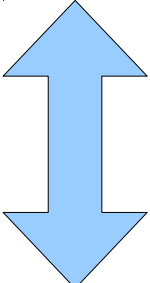
Templates AST

Our plan

Graph



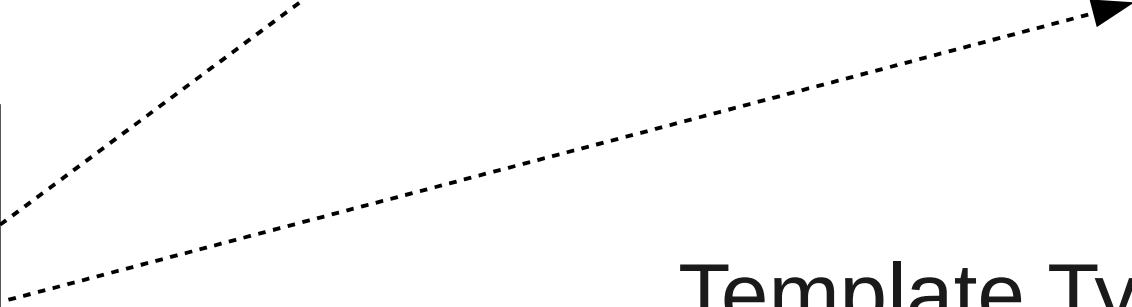
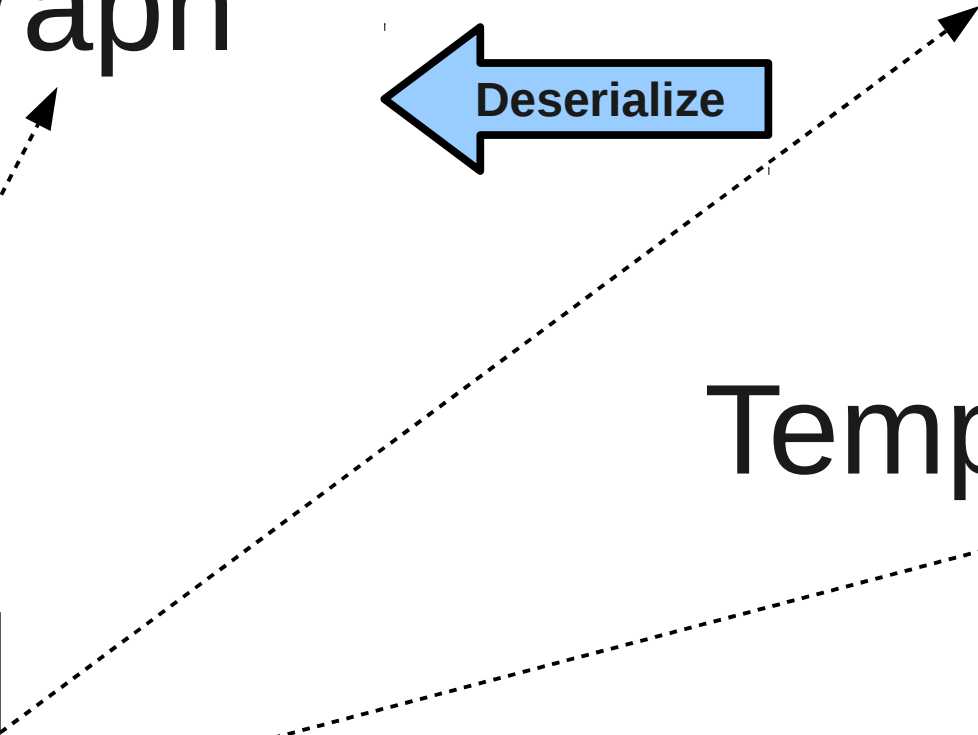
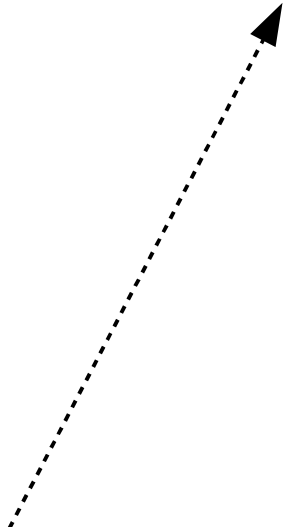
AST



Templates AST

Identification Constraints

Template Type System
must be extended



Identification Constraints

Scope



```
constraint UniqueVarNames for p :: Program {  
  no duplicates in  
    [var.name | var <- p.statements,  
              var is instance of Var]  
}
```

Key



Name Checking for MyToy

```
VAR x = 2; VAR y = 5;  
VAR xy = 0;  
...  
VAR trigger = 0;  
...  
VAR trigger = 0;  
...
```



```
{x, y, xy,  
trigger,  
trigger}
```

- for every scope
 - compute the collection of keys
 - check it for duplicates

Is it sufficient?

- **Yes!**
 - MOF/Ecore
 - EBNF
 - DDL
 - DTD
 - Other language which describe static structures
- **No**
 - Programming languages
 - ...

Types for Name checking

**Forget about names of templates
and their parameters!**

```
template $UNTIL :: defines('trigger', bodyDef)
  <condition> <body :: defines(bodyDef)> {
    VAR trigger = 0; :: defines('trigger')
    comefrom trigger = 1;
    <body> :: defines(bodyDef)
    trigger = 1;
    comefrom <condition>;
  }
```


Name Checking Example

```
VAR x = 2; :: defines('x')
VAR y = 5; :: defines('y')
VAR xy = 0; :: defines('xy')
$UNTIL <x = 0> <
  xy = xy + y;
  x = x - 1;
>; :: defines('trigger')
$UNTIL <y = 0> <
  VAR one = 1;
  y = y - one;
>; :: defines('trigger', 'one')
```

**Error: templates
'UNTIL' and
'UNTIL' define the
same variable:
trigger!**

```
template $UNTIL :: defines('trigger', bodyDef)
```

Naming Errors

- Duplicate definition
 - done
- “Hygienic” templates
 - achievable
- Usage of undefined name (only AST)
 - symmetric
- Illegal context
 - In the graph an object is used while it's name is not visible
- Collision
 - Two distinct objects with the same names are used

Symmary

- If a language is described as (Graph \leftrightarrow AST)
 - Automatically extend it with template support
 - Structural correctness guarantees
 - Some naming correctness guarantees
- Ecore, EBNF, DTD, etc.
 - Complete support for templates
- More complicated languages
 - Subject to future work...

Thanks for your attention!