

ZK proofs

Classical proof idea:

Want $S(x, y) \approx \langle P, V \rangle$

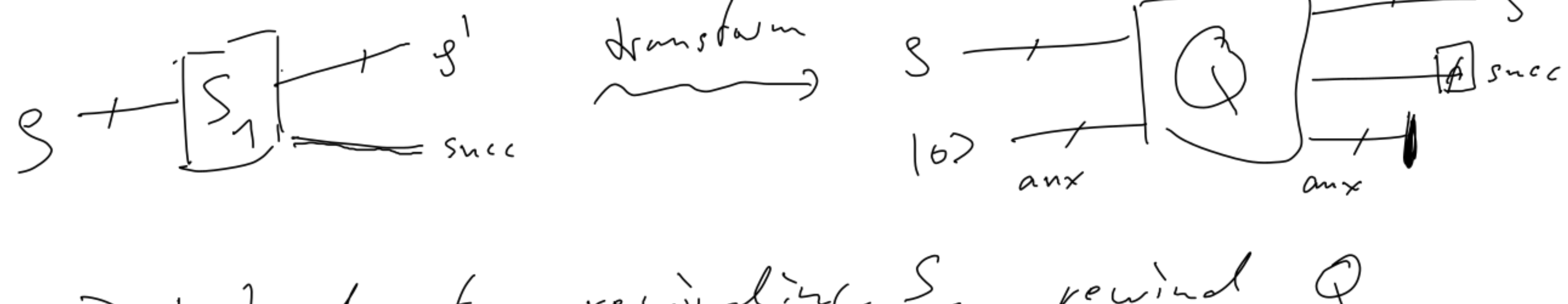
Managed: $S_1(x, y) | \text{about} = \langle P, V \rangle$
 $\Pr[\text{about}] = 1/2$ } also works in Q setting (practice)

Build S_1 :

Run $S_1(x, y) \leftarrow \dots$
 if $\neg \text{about}$: return \dots
 else: restart \dots

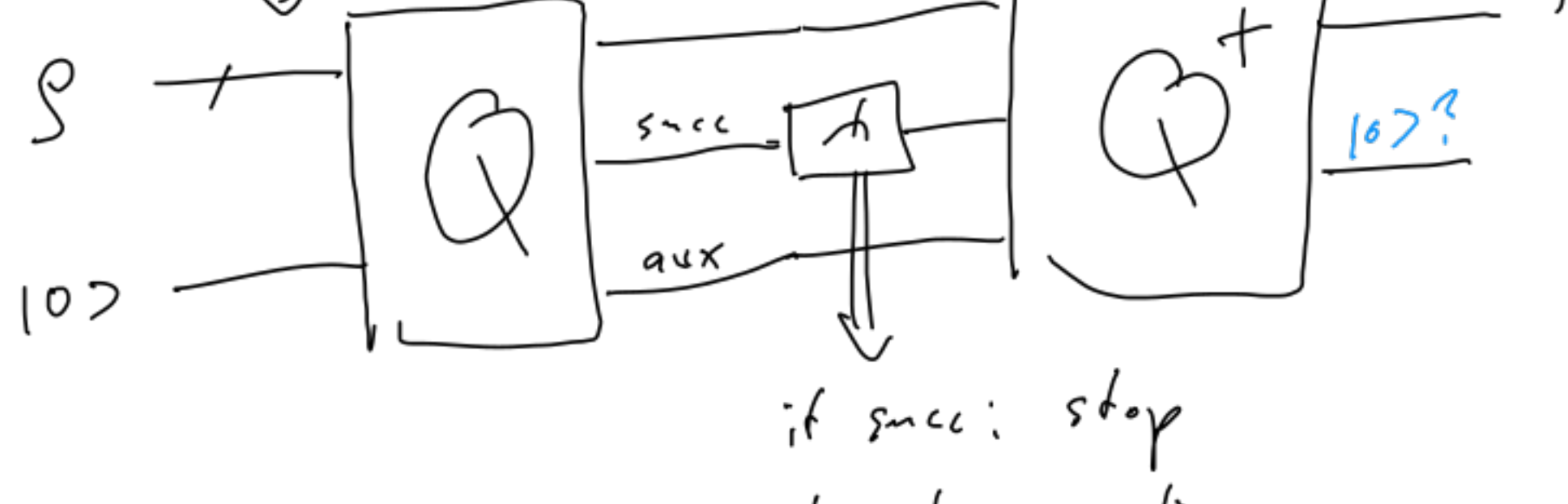
Problem: Cannot copy S to return S_1

First step: Transform S_1 into unitary $S_1 = Q$



⇒ Instead of restarting S_1 , rewind Q

Next attempt at S



if succ: stop
 if not: continue

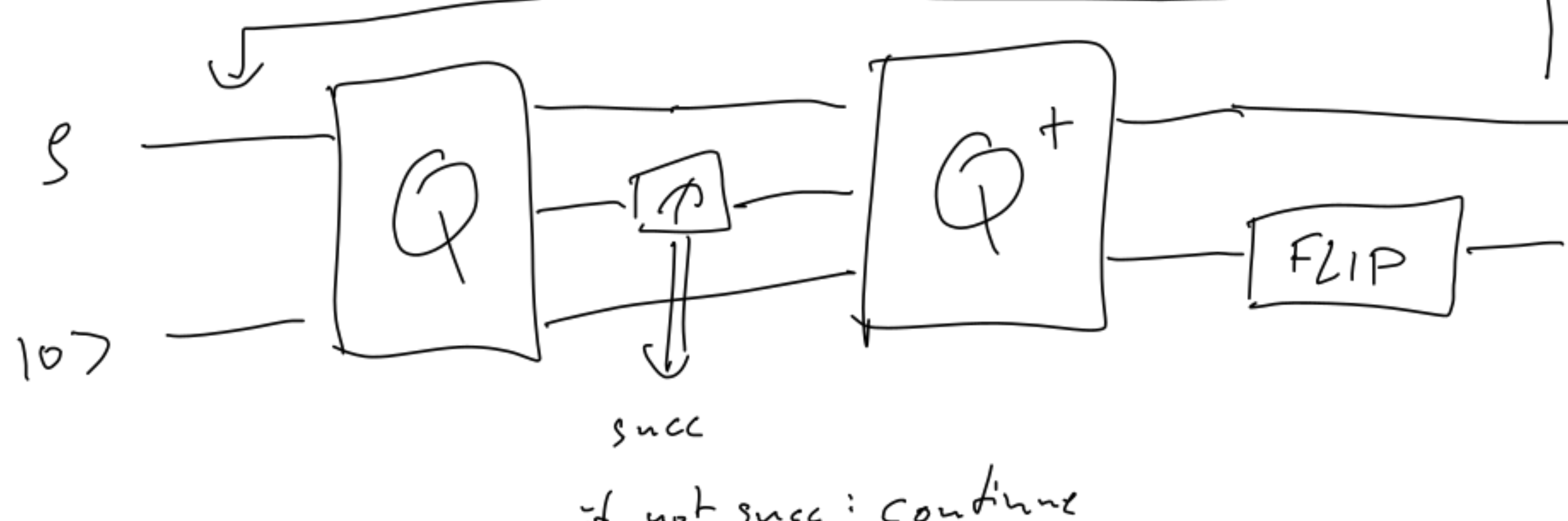
just a binary meas. in different basis

$$P_Q = Q^+ \cdot (I \otimes |0\rangle\langle 0| \otimes I) \cdot Q$$

Two problems:

- Q^+ might not give S back
- Second iteration has 0 success prob.

Second attempt



if not succ: continue

FLIP $|0\rangle \rightarrow |1\rangle$
 FLIP $|x\rangle = -|x\rangle$ ($x \neq 0$)

This works: Cond. on success (after n iterations) we get $\langle P, V \rangle$ what Q outputs cond. on success

- $\Pr[\text{succ}]$ high

Conditions

- Q unitary
- $\Pr[\text{succ in } |0\rangle] = \langle P, V \rangle = p$ for same $p \leq 1/2$ indep. of $|\psi\rangle$

Why does measuring success not disturb? (At least not ruinously)

Because $\Pr[\text{succ}]$ indep. of init state, succ measurement does not measure info about init state ⇒ does not disturb (individually)

Say init. state is $|\psi\rangle = (|\psi\rangle \otimes |\phi\rangle)$

$$P_Q = Q^+ (I \otimes |0\rangle\langle 0| \otimes I) Q$$

$$\| P_Q (|\psi\rangle \otimes |0\rangle) \|^2 = 1-p \quad \forall |\psi\rangle$$

$$\langle \psi | \langle \phi | P_Q^* P_Q (|\psi\rangle \otimes |0\rangle)$$

$$\langle \psi | (I \otimes \langle 0 |) P_Q (I \otimes |0\rangle) |\psi\rangle$$

P_Q^* { init aux $|0\rangle$, run Q , meas; Q^+ , measure if aux = $|0\rangle$

$$\langle \psi | P_Q^* |\psi\rangle$$

$$\Leftrightarrow \langle \psi | P_Q^* |\psi\rangle = 1-p \quad \forall |\psi\rangle$$

$$\langle \psi | (1-p) I |\psi\rangle = 1-p$$

$$\Rightarrow P_Q^* = (1-p) I$$

$|\psi\rangle |0\rangle$ init. state

$$\overline{P_Q} = 1 - P_Q$$

$$|\phi_{\text{succ}}\rangle = \frac{P_Q |\psi\rangle |0\rangle}{\| \dots \|}$$

$$|\phi_{\text{bad}}\rangle = \frac{P_Q |\psi\rangle |0\rangle}{\| \dots \|}$$

$$|\psi\rangle |0\rangle \in \text{span} \{ |\phi_{\text{succ}}\rangle, |\phi_{\text{bad}}\rangle \}$$

First step: P_Q

if succ: $|\phi_{\text{succ}}\rangle$ (done)

$Q |\phi_{\text{succ}}\rangle$ is desired state

if not succ: $|\phi_{\text{bad}}\rangle$

FLIP $\text{span} \{ |\phi_{\text{succ}}\rangle, |\phi_{\text{bad}}\rangle \}$

P_Q

$|\phi_{\text{succ}}\rangle$

$|\phi_{\text{bad}}\rangle$

$|\psi\rangle |0\rangle \in \text{span} \{ |\phi_{\text{succ}}\rangle, |\phi_{\text{bad}}\rangle \}$

FLIP $|\phi_{\text{bad}}\rangle$

$|\psi\rangle |0\rangle$

$|\phi_{\text{succ}}\rangle$

$|\phi_{\text{bad}}\rangle$

Missing piece:

FLIP $|\phi_{\text{bad}}\rangle$ stays in span.

$$\Delta := I \otimes |0\rangle\langle 0|$$

$$\text{FLIP} = 2\Delta - I$$

$$\text{FLIP } |\phi_{\text{bad}}\rangle = \frac{(2\Delta - I) P_Q |\psi\rangle |0\rangle}{\| \dots \| = \sqrt{1-p}}$$

$$= \frac{2\Delta P_Q \Delta |\psi\rangle |0\rangle - P_Q |\psi\rangle |0\rangle}{\sqrt{1-p}}$$

$$= 2 \frac{(I \otimes |0\rangle\langle 0|) (I \otimes \langle 0 |) P_Q (I \otimes |0\rangle) (I \otimes |0\rangle) |\psi\rangle |0\rangle}{\sqrt{1-p}} - \frac{P_Q |\psi\rangle |0\rangle}{\sqrt{1-p}}$$

$$= 2 \frac{\langle \psi | \langle 0 | P_Q^* (I \otimes |0\rangle\langle 0|) P_Q (I \otimes |0\rangle) |\psi\rangle |0\rangle}{\sqrt{1-p}} - \frac{P_Q |\psi\rangle |0\rangle}{\sqrt{1-p}}$$

$$= 2 \sqrt{1-p} |\psi\rangle |0\rangle - |\phi_{\text{bad}}\rangle$$

$$\Rightarrow \text{FLIP } |\phi_{\text{bad}}\rangle = 2\sqrt{1-p} |\psi\rangle |0\rangle - |\phi_{\text{bad}}\rangle$$

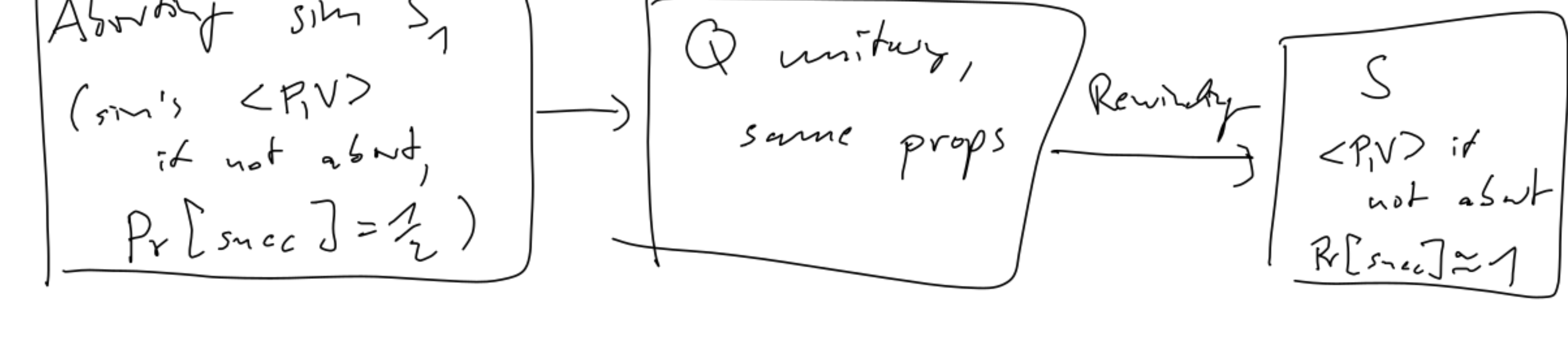
⇒ After FLIP: have a state that gives us succ with prob. $4p(1-p)$

⇒ In fresh ite: $\Pr[\text{succ}] = p$

in every other: $\Pr[\text{succ}] = 4p(1-p)$

⇒ Get succ in $\sim \frac{1}{4p(1-p)}$ iterations

Putting it together:



⇒ GI is QZK.