

Surjectivity and reversibility in cellular automata: A review

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Kääriku, 31 January 2008

Revised: February 4, 2009

Overview

- ▶ Cellular automata (CA) are synchronous distributed systems where the next state of each device only depends on the current state of its neighbors.
- ▶ Their implementation on a computer is straightforward, making them very good tools for simulation and qualitative analysis.
- ▶ It is instead very difficult to recover the properties of the global dynamics by only looking at the local description.

Life is a Game

Invented by John Horton Conway (1960s) popularized by Martin Gardner.

The **checkboard** is an infinite square grid.

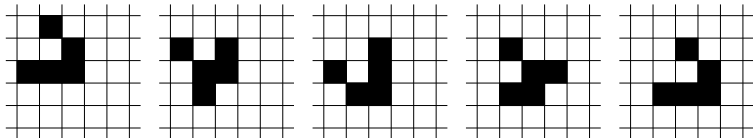
Each case of the checkboard is “surrounded” by those within a chess’ king’s move, and can be “living” or “dead”.

1. A “dead” case surrounded by **exactly three** living cases, **becomes living**.
2. A living case surrounded by **two or three** living cases, **survives**.
3. A living case surrounded by **one or no** living cases, dies of **isolation**.
4. A living case surrounded by **four or more** living cases, dies of **overpopulation**.

Simple rule, complex behavior

The structures of the Game of Life can exhibit a wide range of behaviors.

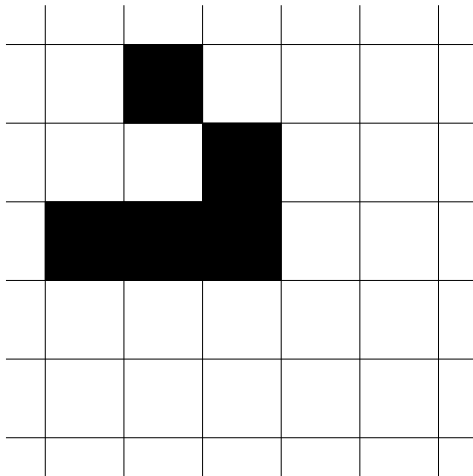
This is a [glider](#), which repeats itself every four iterations, after having moved:



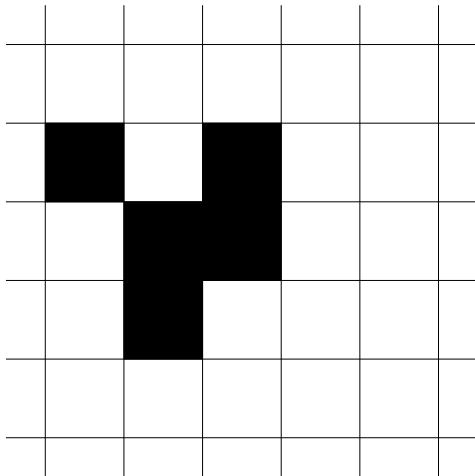
Glider can [transmit information](#) between regions of the checkboard.

Actually, using gliders and other complex structures, any planar circuit can be simulated inside the Game of Life.

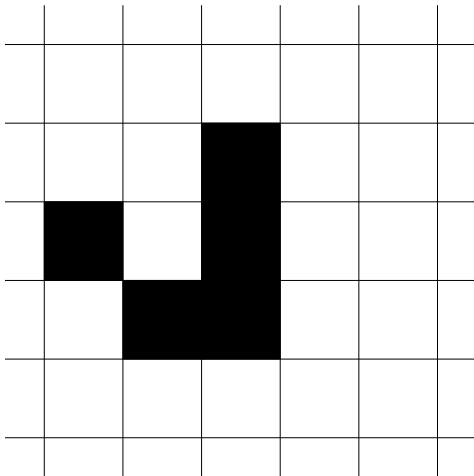
Glider in motion, $t = 0$



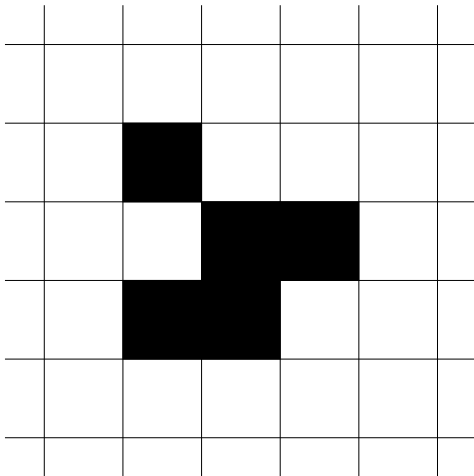
Glider in motion, $t = 1$



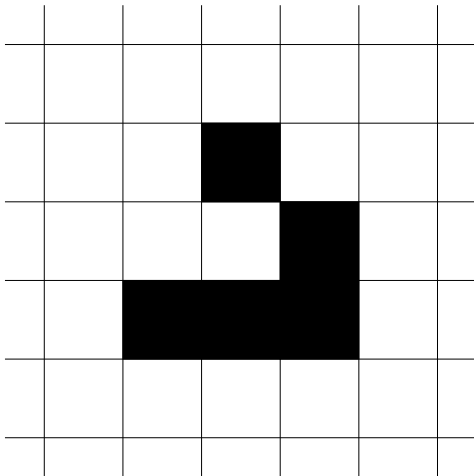
Glider in motion, $t = 2$



Glider in motion, $t = 3$



Glider in motion, $t = 4$



The ingredients of a recipe

A **cellular automaton (CA)** is a quadruple $\mathcal{A} = \langle d, Q, \mathcal{N}, f \rangle$ where

- ▶ $d > 0$ is an integer—**dimension**
- ▶ $Q = \{q_1, \dots, q_n\}$ is finite nonempty—**set of states**
- ▶ $\mathcal{N} = \{n_1, \dots, n_k\}$ is a finite subset of \mathbb{Z}^d —**neighborhood**
- ▶ $f : Q^{\mathcal{N}} \rightarrow Q$ is a function—**local map**

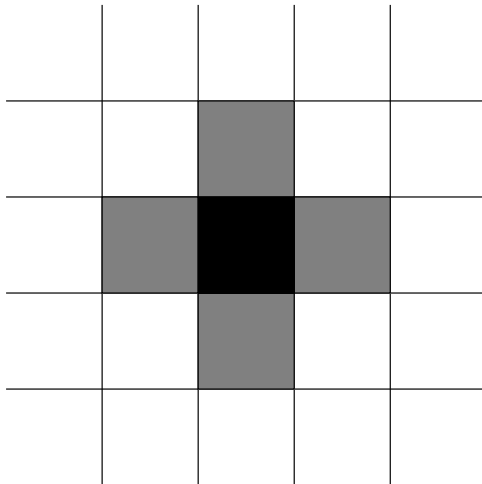
Special neighborhoods are:

- ▶ the **von Neumann** neighborhood of radius r

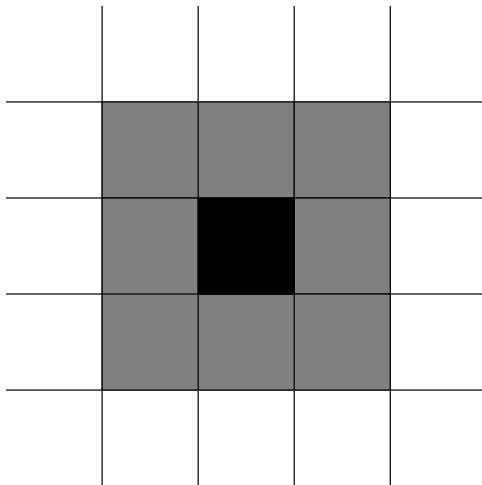
$$vN(r) = \{x \in \mathbb{Z}^d \mid \sum_{i=1}^d |x_i| \leq r\}$$
- ▶ the **Moore** neighborhood of radius r

$$M(r) = \{x \in \mathbb{Z}^d \mid \max_{1 \leq i \leq d} |x_i| \leq r\}$$

For $d = 2$, this is von Neumann's neighborhood $vN(1)$...



and this is Moore's neighborhood $M(1)$.



Configurations

A d -dimensional **configuration** is a map $c : \mathbb{Z}^d \rightarrow Q$.

We consider the following distance on configurations:

if c_1 and c_2 differ on $M(n)$ but coincide on $M(n-1)$
 then $d_M(c_1, c_2) = 2^{-n}$

Two configurations are “near” according to d_M iff they are “equal on a large zone around the origin”.

d_M induces the **product topology**—which makes $Q^{\mathbb{Z}^d}$ **compact**.

We also consider **translations** given by

$$c^x(y) = c(x + y) \text{ for all } y \in \mathbb{Z}^d$$

From local to global

Let $\mathcal{A} = \langle d, Q, \mathcal{N}, f \rangle$ be a CA.

The **global map** of \mathcal{A} is $F_{\mathcal{A}} : Q^{\mathbb{Z}^d} \rightarrow Q^{\mathbb{Z}^d}$ defined by

$$(F_{\mathcal{A}}(c))(x) = f(c(x + n_1), \dots, c(x + n_k))$$

We say that \mathcal{A} is injective, surjective, etc. if $F_{\mathcal{A}}$ is.

Hedlund's theorem (1969)

Let $F : Q^{\mathbb{Z}^d} \rightarrow Q^{\mathbb{Z}^d}$.

The following are equivalent:

1. F is a CA global map
2. F is continuous and commutes with the translations

Reason why:

- ▶ translation invariance \Rightarrow only need to determine $F(c)(0)$
- ▶ $Q^{\mathbb{Z}^d}$ compact $\Rightarrow F$ uniformly continuous $\Rightarrow F(c)(0)$ only depends on $c|_{M(n)}$ for n large enough

Consequence: a composition of CA yields a CA.
(This can also be seen from the local rules.)

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Special configurations and states

- ▶ **Periodic configurations** cover the d -dimensional space with a repeated regular pattern.
- ▶ **q -finite configurations** only have finitely many points in states other than q .
- ▶ **Quiescent states** satisfy $f(q, \dots, q) = q$.
In this case, we call $\mathcal{A}_{(q)}$ the restriction of \mathcal{A} to q -finite configurations.

The state 0 in Conway's Game of Life is quiescent.

Garden-of-Eden configuration and orphan patterns

A **Garden-of-Eden (GoE)** for a CA \mathcal{A} is a configuration c that has no predecessor according to the global law of \mathcal{A} —that is,

$$F_{\mathcal{A}}(c') \neq c \quad \forall c' \in Q^{\mathbb{Z}^d}$$

A pattern p is **orphan** if every configuration where it occurs is a GoE.

An orphan pattern for a simple CA

Consider the **AND** CA on two neighbors

- ▶ $d = 1$
- ▶ $Q = \{0, 1\}$
- ▶ $\mathcal{N} = \{0, 1\}$
- ▶ $f(a, b) = a \text{ AND } b$

The pattern 101 is orphan:

...	1	0	1
...	1	1	1	1	...
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1. \mathcal{A} has a GoE configuration
2. \mathcal{A} has an orphan pattern

The Garden-of-Eden lemma

Let \mathcal{A} be a CA. The following are equivalent:

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Proof:

- ▶ For each n , consider the restriction p_n of c to $M(n)$.
- ▶ \mathcal{A} has no orphan pattern \Rightarrow each p_n has a predecessor \Rightarrow extend that to a configuration c'_n .
- ▶ $Q^{\mathbb{Z}^d}$ compact \Rightarrow the sequence $\{c'_n\}$ has a limit point c' .
- ▶ Then $F_{\mathcal{A}}(c') = c$ by continuity.

Corollary: CA surjectivity is co-r.e.

Reason why: try all patterns until one has no predecessors.

“Not injectivity, but almost”

Cellular automata are “not finitar, but almost”.

It seems reasonable that surjectivity for CA may be equivalent to “not injectivity, but almost”.

Say that two distinct patterns $p_1, p_2 : E \rightarrow Q$ are **mutually erasable (m.e.)** for \mathcal{A} if

- ▶ $(c_i)|_E = p_i$ and
- ▶ $(c_1)|_{\mathbb{Z}^d \setminus E} = (c_2)|_{\mathbb{Z}^d \setminus E}$

imply $F_{\mathcal{A}}(c_1) = F_{\mathcal{A}}(c_2)$.

Call **pre-injective** a CA that has no two m.e. patterns.

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Moore-Myhill's theorem (1962)

The following are equivalent:

1. \mathcal{A} is surjective
2. \mathcal{A} is pre-injective

Reason why:

- ▶ Call **boundary** of E (w.r.t. \mathcal{N}) the sets of neighbors of points of E that are not in E
- ▶ Then the size of the boundary of a d D hypercube is bounded by a polynomial of degree $d - 1$
- ▶ The thesis follows by a counting argument

Corollary: (Richardson, 1972)

1. **injective CA are surjective**
2. if \mathcal{A} has a quiescent state q , then

$$\mathcal{A} \text{ surjective} \Leftrightarrow \mathcal{A}_{(q)} \text{ injective}$$

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A surjective, non-injective CA

Let $d = 1$, $Q = \{0, 1\}$, $\mathcal{N} = \{-1, 0, 1\}$, $f(a, b, c) = a \oplus c$,

- Non-injectivity: put

$$c_0(x) = 0 \quad \forall x \in \mathbb{Z} ; \quad c_1(x) = 1 \quad \forall x \in \mathbb{Z}$$

then $F_{\mathcal{A}}(c_0) = F_{\mathcal{A}}(c_1) = c_0$.

- Surjectivity:
 1. for every a and k , the equation $a \oplus x = k$ has a unique solution
 2. for every b and k , the equation $x \oplus b = k$ has a unique solution

Thus every configuration has exactly **four** predecessors.

Balancement

Let $\mathcal{A} = \langle d, Q, M(r), f \rangle$ be a CA.

(Observe that all CA may be written as such.)

For each n , define $F_n : Q^{\{1, \dots, n+2r\}^d} \rightarrow Q^{\{1, \dots, n\}^d}$ as

$$(F_n(p))(x) = f(p(x + n_1), \dots, p(x + n_{|M(r)|}))$$

We say that \mathcal{A} is **n -balanced** if

$$|(F_n(p))^{-1}| = Q^{(n+2r)^d - n^d} \quad \forall p \in Q^{\{1, \dots, n+2r\}^d},$$

i.e., if every pattern on a d -hypercube of side n has the same number of pre-images.

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A 1-balanced, nonsurjective CA

The **majority CA** is defined by the local function

$$f(a, b, c) = \begin{cases} 0 & \text{if } a + b + c \leq 1 \\ 1 & \text{if } a + b + c \geq 2 \end{cases}$$

Then the string 01001 is a GoE:

...	0	1	0	0	1	...
...	1	0	1	0	0	...
...					↑	...
...	0	1	0		...	
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The balancement theorem (Maruoka and Kimura, 1976)

Let $\mathcal{A} = \langle d, Q, M(r), f \rangle$, $U \subseteq \mathbb{Z}^d$. The following are equivalent:

1. \mathcal{A} is surjective
2. \mathcal{A} is n -balanced for all n

Reason why:

- ▶ Boundary grows slower than support
- ▶ If n -balanced for all n then no pattern is orphan
- ▶ If not n -balanced for some n , employ “rarest” patterns to find (larger) orphan pattern

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Loss of output state in CA

- ▶ The Garden-of-Eden theorem says that non-surjective CA are precisely those that **lose output state within finite range**
- ▶ How does one measure the **amount** of lost state?

Given $\mathcal{A} = \langle d, Q, \mathcal{N}, f \rangle$, let $\text{Out}_f(n)$ be the number of non-orphan patterns with support a d -hypercube of side n .

Consider then the **loss of state at side n**

$$\Lambda_{\mathcal{A}}(n) = n^d - \log_{|Q|} \text{Out}_f(n)$$

measured in **qits** ($q = |Q|$; 1 qit = $\log_2 q$ bits)

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How much information do non-surjective CA lose?

Theorem (Capobianco, 2008)

If \mathcal{A} is non-surjective then $\lim_{n \rightarrow \infty} \Lambda_{\mathcal{A}}(n) = +\infty$

Proof: (for $d = 1$)

- ▶ “Large” non-orphan is juxtaposition of “small” non-orphans
 $\Rightarrow \text{Out}_f(m+n) \leq \text{Out}_f(m) \cdot \text{Out}_f(n)$ for all m and n
- ▶ By Fekete's lemma, there exists $\delta < 1$ such that

$$\frac{\log_{|Q|} \text{Out}_f(n)}{n} < \delta$$

for all n large enough

- ▶ For those values of n , $\Lambda_{\mathcal{A}}(n) > n \cdot (1 - \delta)$

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Reversibility

A CA \mathcal{A} is **reversible** if

1. \mathcal{A} is invertible, and
2. $F_{\mathcal{A}}^{-1}$ is the global evolution function of some CA.

Thus, a CA is reversible iff the **reverse CA** exists.

This seems more than just existence of inverse global evolution.

Reversible CA are important in physical modelization because

Physics, at microscopical scale, is reversible.

Fact CA reversibility is r.e.

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Richardson's reversibility principle (1972)

The following are equivalent:

1. \mathcal{A} is reversible
2. \mathcal{A} is bijective

Thus, existence of inverse CA comes at no cost from existence of inverse global evolution.

Reason why:

- ▶ $Q^{\mathbb{Z}^d}$ compact metrizable $\Rightarrow F_{\mathcal{A}}^{-1}$ continuous
- ▶ $F_{\mathcal{A}}$ commutes with shift $\Rightarrow F_{\mathcal{A}}^{-1}$ does
- ▶ apply Hedlund's theorem

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A scheme of the current situation

Reversible (r.e.)	Properly Surjective	Non-Surjective (r.e.)
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Can reversibility be checked?

Let \mathcal{C} be a class of cellular automata.

The **invertibility problem** for \mathcal{C} states:

given an element \mathcal{A} of \mathcal{C} ,
determine whether $F_{\mathcal{A}}$ is invertible.

Meaning: invertibility of the **global dynamics** of any CA in \mathcal{C} can be inferred **algorithmically** by looking at its **local description**.

One is too little...

Theorem (Amoroso and Patt, 1972)

The invertibility problem for 1D CA is decidable.

Reason why:

- ▶ surjectivity of 1D CA can be determined via a suitable graph
- ▶ injectivity of 1D surjective CA can be checked “within finite range”

Additional results:

1. surjectivity of 1D CA is decidable.
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... but two is too much

“Although the techniques we employ are in principle adaptable to arrays of higher dimension, it turns out that they are difficult to manage beyond dimension one.”

Theorem (Kari, 1990)

The invertibility problem for 2D CA—and consequently for d D CA with $d > 2$ —is **und**ecidable.

Reason why: undecidability of Hao Wang’s Tiling Problem:

given a set of square tiles with colored sides,
determine if there is a tiling of the plane
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Kari's method

- ▶ Consider a set of tiles T .
- ▶ Consider a special set of tiles S , whose tiles also have **arrows**. (This set has a special, “plane filling” property.)
- ▶ Construct a CA with $Q = T \times S \times \{0, 1\}$ and whose rule says:
 - ▶ if both tilings are correct then XOR with pointed neighbor
 - ▶ otherwise do nothing
- ▶ Then there is a valid tiling with T iff the CA is non-reversible.

Corollary: for $d \geq 2$ there is no computable bound for inverse neighborhood radius.

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- ▶ Construct a CA with $Q = T \times S \times \{0, 1\}$ and whose rule says:
 - ▶ if both tilings are correct then XOR with pointed neighbor
 - ▶ otherwise do nothing
- ▶ Then there is a valid tiling with T iff the CA is non-reversible.

Corollary: for $d \geq 2$ there is no computable bound for inverse neighborhood radius.

From infinite to finite

- ▶ For now, we have only considered CA on infinite grids.
- ▶ We now consider laws induced the same way, on **toroidal** supports—equivalently, on **periodic** configurations.
- ▶ If $\mathcal{A} = \langle d, Q, \mathcal{N}, f \rangle$ and a hypercube of side n contains \mathcal{N} , call \mathcal{A}_n the transformation induced by \mathcal{A} on $Q^{(\mathbb{Z}/n\mathbb{Z})^d}$.
- ▶ We call **locally non-reversible** those CA local rules that induce non-surjective transformations for some values of the size n .

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Local (non-)reversibility

Local reversibility is co-r.e.

- ▶ **Reason why:** Try all **periodic** configurations until a GoE is found.

Reversible CA are locally reversible.

- ▶ **Reason why:** \mathcal{A} reversible \Rightarrow (pre)image of a periodic configuration is also periodic—with same period(s)

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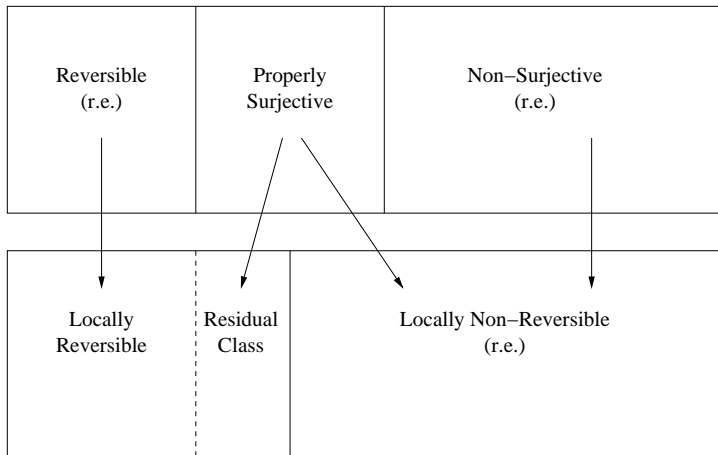
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A scheme of the updated situation



The residual class (Toffoli and Margolus, 1990)

It is made of local rules that

- ▶ always determine reversible CA on hypercubes
- ▶ always determine properly surjective CA on the whole space

It is non-r.e. (in particular, non-empty)

Reason why:

- ▶ Suppose otherwise
- ▶ Then global non-reversibility is union of r.e. properties
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The complexity issue

We can consider the finitary version of the invertibility problem:

given \mathcal{A} and n ,
determine if \mathcal{A}_n is reversible

Theorem (Clementi, 1994)

The invertibility problem for hypercubic CA is co-NP-complete.

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Suggested readings

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Thank you for attention!

Any questions?