

Asymptotic Goodness of Expander Codes with Weak Constituent Codes

Vitaly Skachek

This work is a part of the speaker's Ph.D. Thesis.
It was done at the Technion – Israel Institute of Technology
under the supervision of Ron M. Roth.

LDPC Codes

Low-density parity-check codes.

- ▶ [Gallager '62] Presented for the first time. Seemed to be unpractical then.

LDPC Codes

Low-density parity-check codes.

- ▶ [Gallager '62] Presented for the first time. Seemed to be unpractical then.
- ▶ [Berrou, Glavieux, Thitimajshima '93] Turbo codes, which are extremely efficient in practice, stimulated a new wave of research on LDPC codes.

LDPC Codes

Low-density parity-check codes.

- ▶ [Gallager '62] Presented for the first time. Seemed to be unpractical then.
- ▶ [Berrou, Glavieux, Thitimajshima '93] Turbo codes, which are extremely efficient in practice, stimulated a new wave of research on LDPC codes.
- ▶ [Richardson Urbanke '01] Good *average* behavior over binary memoryless channels.

LDPC Codes

Low-density parity-check codes.

- ▶ [Gallager '62] Presented for the first time. Seemed to be unpractical then.
- ▶ [Berrou, Glavieux, Thitimajshima '93] Turbo codes, which are extremely efficient in practice, stimulated a new wave of research on LDPC codes.
- ▶ [Richardson Urbanke '01] Good *average* behavior over binary memoryless channels.
- ▶ [Richardson Shokrollahi Urbanke '01] Codes, which are extremely close to the capacity, found by the exhaustive search.

Explicit Constructions

- ▶ [Sipser Spielman '96] Correct constant fraction of errors, linear time encoding and decoding.

Explicit Constructions

- ▶ [Sipser Spielman '96] Correct constant fraction of errors, linear time encoding and decoding.
- ▶ [Barg Zémor '01–'04] Capacity-achieving codes for BSC with linear-time decoding, exponentially small decoding error. Binary codes that surpass the Zyablov bound.

Basic Definitions

Basic Definitions

Definition

Code \mathcal{C} is a set of words of length n over an alphabet Σ .

Basic Definitions

Definition

Code \mathcal{C} is a set of words of length n over an alphabet Σ .

Definition

- ▶ The Hamming distance between $\mathbf{x} = (x_1, \dots, x_n)$ and $\mathbf{y} = (y_1, \dots, y_n)$ in Σ^n , $d(\mathbf{x}, \mathbf{y})$, is the number of pairs of symbols (x_i, y_i) , $1 \leq i \leq n$, such that $x_i \neq y_i$.

Basic Definitions

Definition

Code \mathcal{C} is a set of words of length n over an alphabet Σ .

Definition

- ▶ The *Hamming distance* between $\mathbf{x} = (x_1, \dots, x_n)$ and $\mathbf{y} = (y_1, \dots, y_n)$ in Σ^n , $d(\mathbf{x}, \mathbf{y})$, is the number of pairs of symbols (x_i, y_i) , $1 \leq i \leq n$, such that $x_i \neq y_i$.
- ▶ The *minimum distance* of a code \mathcal{C} is

$$d = \min_{\mathbf{x}, \mathbf{y} \in \mathcal{C}, \mathbf{x} \neq \mathbf{y}} d(\mathbf{x}, \mathbf{y}).$$

Basic Definitions

Definition

Code \mathcal{C} is a set of words of length n over an alphabet Σ .

Definition

- ▶ The Hamming distance between $\mathbf{x} = (x_1, \dots, x_n)$ and $\mathbf{y} = (y_1, \dots, y_n)$ in Σ^n , $d(\mathbf{x}, \mathbf{y})$, is the number of pairs of symbols (x_i, y_i) , $1 \leq i \leq n$, such that $x_i \neq y_i$.
- ▶ The minimum distance of a code \mathcal{C} is

$$d = \min_{\mathbf{x}, \mathbf{y} \in \mathcal{C}, \mathbf{x} \neq \mathbf{y}} d(\mathbf{x}, \mathbf{y}).$$

- ▶ The relative minimum distance of \mathcal{C} is defined as $\delta = d/n$.

Linear Code

Definition

- ▶ A code \mathcal{C} over field Φ is said to be a *linear* $[n, k, d]$ code if there exists a matrix H with n columns and rank $n - k$ such that

$$Hx^t = \bar{\mathbf{0}} \Leftrightarrow x \in \mathcal{C}.$$

- ▶ The matrix H is called a *parity-check matrix*.
- ▶ The value k is called the *dimension* of the code \mathcal{C} .
- ▶ The ratio $r = k/n$ is called the *rate* of the code \mathcal{C} .
- ▶ The words of \mathcal{C} can be obtained as linear combinations of rows of a *generating* $k \times n$ matrix G .

LDPC and Low-Complexity Codes

[Gallager '62]

- ▶ Matrix H : the number of non-zero entries in each column (row) of H is typically *bounded by a small constant*.

LDPC and Low-Complexity Codes

[Gallager '62]

- ▶ Matrix H : the number of non-zero entries in each column (row) of H is typically *bounded by a small constant*.

[Tanner '81]

- ▶ A Δ -regular undirected graph $\mathcal{G} = (V, E)$ with $|E| = N$.

LDPC and Low-Complexity Codes

[Gallager '62]

- ▶ Matrix H : the number of non-zero entries in each column (row) of H is typically *bounded by a small constant*.

[Tanner '81]

- ▶ A Δ -regular undirected graph $\mathcal{G} = (V, E)$ with $|E| = N$.
- ▶ Linear $[\Delta, k=r\Delta, d=\delta\Delta]$ code \mathcal{C} over $\text{GF}(q)$.

$\mathbb{C} = (\mathcal{G}, \mathcal{C})$ is the following linear $[N, K, D]$ code over $\text{GF}(q)$:

$$\mathbb{C} = \{ \mathbf{c} \in (\text{GF}(q))^N : (\mathbf{c})_{E(v)} \in \mathcal{C} \text{ for every } v \in V \} ,$$

$(\mathbf{c})_{E(v)}$ = the sub-word of \mathbf{c} that is indexed by the set of edges incident with v .

LDPC and Low-Complexity Codes

[Gallager '62]

- ▶ Matrix H : the number of non-zero entries in each column (row) of H is typically *bounded by a small constant*.

[Tanner '81]

- ▶ A Δ -regular undirected graph $\mathcal{G} = (V, E)$ with $|E| = N$.
- ▶ Linear $[\Delta, k=r\Delta, d=\delta\Delta]$ code \mathcal{C} over $\text{GF}(q)$.

$\mathbb{C} = (\mathcal{G}, \mathcal{C})$ is the following linear $[N, K, D]$ code over $\text{GF}(q)$:

$$\mathbb{C} = \{ \mathbf{c} \in (\text{GF}(q))^N : (\mathbf{c})_{E(v)} \in \mathcal{C} \text{ for every } v \in V \} ,$$

$(\mathbf{c})_{E(v)}$ = the sub-word of \mathbf{c} that is indexed by the set of edges incident with v .

- ▶ The code $\mathbb{C} = (\mathcal{G}, \mathcal{C})$ is a *low-complexity* code.

Low-Complexity Codes – Example

Take $\Delta = 3$, $k = 2$, $|V| = 4$.

Let G be a generating matrix of \mathcal{C}
 over $F = \text{GF}(2^2) = \{0, 1, \alpha, \alpha^2\}$:

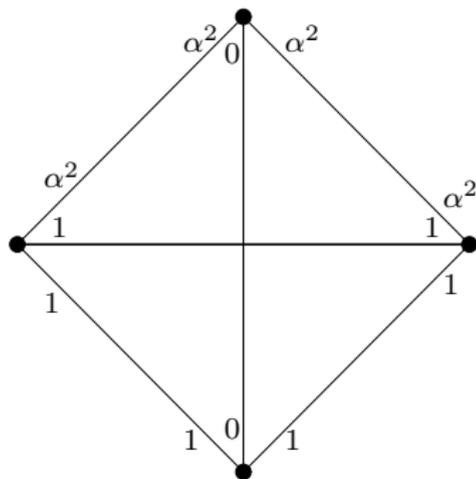
$$G = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & \alpha \end{pmatrix}.$$

Low-Complexity Codes – Example

Take $\Delta = 3$, $k = 2$, $|V| = 4$.

Let G be a generating matrix of \mathcal{C}
 over $F = \text{GF}(2^2) = \{0, 1, \alpha, \alpha^2\}$:

$$G = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & \alpha \end{pmatrix}.$$



Low-Complexity Codes – Example

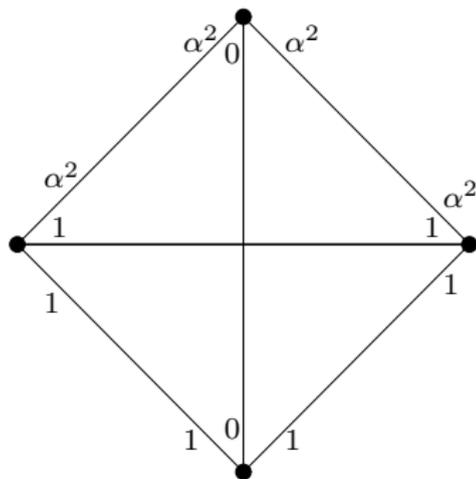
Take $\Delta = 3$, $k = 2$, $|V| = 4$.

Let G be a generating matrix of \mathcal{C}
 over $F = \text{GF}(2^2) = \{0, 1, \alpha, \alpha^2\}$:

$$G = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & \alpha \end{pmatrix}.$$

The resulting code \mathcal{C} is of length
 $N = 6$. For instance,

$$(1 \ 1 \ \alpha^2 \ 0 \ \alpha^2 \ 1) \in \mathcal{C}.$$



Expander Graph

- ▶ Consider a Δ -regular graph $\mathcal{G} = (V, E)$.

Expander Graph

- ▶ Consider a Δ -regular graph $\mathcal{G} = (V, E)$.
- ▶ A subset $S \subseteq V$ *expands by a factor of* ζ , $0 < \zeta \leq 1$, if

$$|\{v \in V : \exists \tilde{v} \in S \text{ such that } \{v, \tilde{v}\} \in E\}| \geq \zeta \Delta \cdot |S|.$$

Expander Graph

- ▶ Consider a Δ -regular graph $\mathcal{G} = (V, E)$.
- ▶ A subset $S \subseteq V$ *expands by a factor of* ζ , $0 < \zeta \leq 1$, if

$$|\{v \in V : \exists \tilde{v} \in S \text{ such that } \{v, \tilde{v}\} \in E\}| \geq \zeta \Delta \cdot |S|.$$

- ▶ The graph \mathcal{G} is an (α, ζ) -*expander* if every subset of at most $\alpha|V|$ vertices expands by a factor of ζ .

Eigenvalues of Expander Graph

- ▶ Consider a graph \mathcal{G} where each vertex has degree Δ . The largest eigenvalue of the adjacency matrix $A_{\mathcal{G}}$ of \mathcal{G} is Δ .

Eigenvalues of Expander Graph

- ▶ Consider a graph \mathcal{G} where each vertex has degree Δ . The largest eigenvalue of the adjacency matrix $A_{\mathcal{G}}$ of \mathcal{G} is Δ .
- ▶ Let $\lambda_{\mathcal{G}}$ be the second largest eigenvalue of $A_{\mathcal{G}}$.

Eigenvalues of Expander Graph

- ▶ Consider a graph \mathcal{G} where each vertex has degree Δ . The largest eigenvalue of the adjacency matrix $A_{\mathcal{G}}$ of \mathcal{G} is Δ .
- ▶ Let $\lambda_{\mathcal{G}}$ be the second largest eigenvalue of $A_{\mathcal{G}}$.
- ▶ Lower ratios of $\gamma_{\mathcal{G}} = \frac{\lambda_{\mathcal{G}}}{\Delta}$ correspond to greater values ζ of expansion. [Alon '86]

Eigenvalues of Expander Graph (cont.)

- ▶ Expander graph with

$$\lambda_G \leq 2\sqrt{\Delta - 1}$$

is called a *Ramanujan graph*.

Eigenvalues of Expander Graph (cont.)

- ▶ Expander graph with

$$\lambda_G \leq 2\sqrt{\Delta - 1}$$

is called a *Ramanujan graph*.

- ▶ Constructions are due to [Lubotsky Philips Sarnak '88], [Margulis '88].

Eigenvalues of Expander Graph (cont.)

- ▶ Expander graph with

$$\lambda_G \leq 2\sqrt{\Delta - 1}$$

is called a *Ramanujan graph*.

- ▶ Constructions are due to [Lubotsky Philips Sarnak '88], [Margulis '88].
- ▶ For Ramanujan graphs, $\zeta \approx \frac{1}{2}$. Eigenvalue approach cannot provide better bounds on ζ [Kahale '95].

Expansion of Expander Graph

- ▶ Expander graph with $\zeta = 1 - \epsilon$ is called a *lossless expander*.

Expansion of Expander Graph

- ▶ Expander graph with $\zeta = 1 - \epsilon$ is called a *lossless expander*.
- ▶ Constructions of *left-regular* bipartite expanders are due to [Reingold Vadhan Wigderson '00], [Capalbo *et al.* '02].

Expansion of Expander Graph

- ▶ Expander graph with $\zeta = 1 - \epsilon$ is called a *lossless expander*.
- ▶ Constructions of *left-regular* bipartite expanders are due to [Reingold Vadhan Wigderson '00], [Capalbo *et al.* '02].
- ▶ For these graphs, $\gamma_G = O(1/\Delta^{1/3})$.

Expander Code Construction

[Sipser Spielman '96], [Barg Zémor '01 - '04].

- ▶ Graph $\mathcal{G} = (V, E)$ is a Δ -regular bipartite undirected graph.

Expander Code Construction

[Sipser Spielman '96], [Barg Zémor '01 - '04].

- ▶ Graph $\mathcal{G} = (V, E)$ is a Δ -regular bipartite undirected graph.
 - ▶ Vertex set $V = A \cup B$ such that $A \cap B = \emptyset$ and $|A| = |B| = n$.
 - ▶ Edge set E of size $n\Delta$ such that every edge in E has one endpoint in A and one endpoint in B .

Expander Code Construction

[Sipser Spielman '96], [Barg Zémor '01 - '04].

- ▶ Graph $\mathcal{G} = (V, E)$ is a Δ -regular bipartite undirected graph.
 - ▶ Vertex set $V = A \cup B$ such that $A \cap B = \emptyset$ and $|A| = |B| = n$.
 - ▶ Edge set E of size $n\Delta$ such that every edge in E has one endpoint in A and one endpoint in B .
- ▶ Linear $[\Delta, k=r_A\Delta, \delta_A\Delta]$ and $[\Delta, r_B\Delta, \delta_B\Delta]$ codes \mathcal{C}_A and \mathcal{C}_B , respectively, over $F = \text{GF}(q)$.

Expander Code Construction (cont.)

\mathbb{C} is a linear code of length $|E|$ over F :

$$\mathbb{C} = \left\{ \mathbf{c} \in F^{|E|} : \begin{array}{l} (\mathbf{c})_{E(u)} \in \mathcal{C}_A \text{ for every } u \in A \text{ and} \\ (\mathbf{c})_{E(u)} \in \mathcal{C}_B \text{ for every } u \in B \end{array} \right\},$$

where $(\mathbf{c})_{E(u)} =$ the sub-word of \mathbf{c} that is indexed by the set of edges incident with u .

Example

Take $k = 2$, $\Delta = 3$, $n = 4$.

Let G_A and G_B be generating matrices of \mathcal{C}_A and \mathcal{C}_B

(respectively) over

$F = \text{GF}(2^2) = \{0, 1, \alpha, \alpha^2\}$:

$$G_A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & \alpha & 0 \end{pmatrix},$$

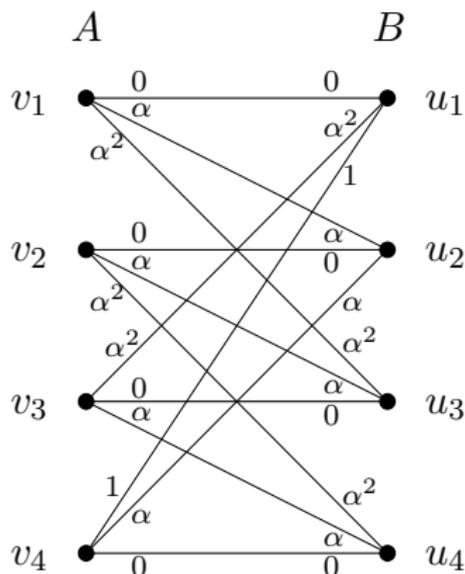
$$G_B = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & \alpha \end{pmatrix}.$$

Example

Take $k = 2$, $\Delta = 3$, $n = 4$.
 Let G_A and G_B be generating
 matrices of \mathcal{C}_A and \mathcal{C}_B
 (respectively) over
 $F = \text{GF}(2^2) = \{0, 1, \alpha, \alpha^2\}$:

$$G_A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & \alpha & 0 \end{pmatrix},$$

$$G_B = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & \alpha \end{pmatrix}.$$



Parameters of Expander Codes

The Code Rate

$$\mathcal{R} \geq r_A + r_B - 1.$$

Parameters of Expander Codes

The Code Rate

$$\mathcal{R} \geq r_A + r_B - 1.$$

Relative Minimum Distance

[Roth Skachek '04]

$$D \geq N \cdot \frac{\delta_A \delta_B - \gamma_{\mathcal{G}} \sqrt{\delta_A \delta_B}}{1 - \gamma_{\mathcal{G}}}.$$

Asymptotic Goodness

Definition

A family of codes $\{C_i\}_{i=0}^{\infty}$, where each C_i is a $[n_i, k_i, d_i]$ linear code, is said to be *asymptotically good* if it satisfies the following conditions:

- ▶ The length n_i of C_i approaches infinity as $i \rightarrow \infty$.

Asymptotic Goodness

Definition

A family of codes $\{C_i\}_{i=0}^{\infty}$, where each C_i is a $[n_i, k_i, d_i]$ linear code, is said to be *asymptotically good* if it satisfies the following conditions:

- ▶ The length n_i of C_i approaches infinity as $i \rightarrow \infty$.
- ▶ $\lim_{i \rightarrow \infty} \frac{d_i}{n_i} = \delta > 0$

Asymptotic Goodness

Definition

A family of codes $\{C_i\}_{i=0}^{\infty}$, where each C_i is a $[n_i, k_i, d_i]$ linear code, is said to be *asymptotically good* if it satisfies the following conditions:

- ▶ The length n_i of C_i approaches infinity as $i \rightarrow \infty$.
- ▶ $\lim_{i \rightarrow \infty} \frac{d_i}{n_i} = \delta > 0$
- ▶ $\lim_{i \rightarrow \infty} \frac{k_i}{n_i} = \mathcal{R} > 0$

Asymptotic Goodness

Definition

A family of codes $\{C_i\}_{i=0}^{\infty}$, where each C_i is a $[n_i, k_i, d_i]$ linear code, is said to be *asymptotically good* if it satisfies the following conditions:

- ▶ The length n_i of C_i approaches infinity as $i \rightarrow \infty$.
- ▶ $\lim_{i \rightarrow \infty} \frac{d_i}{n_i} = \delta > 0$
- ▶ $\lim_{i \rightarrow \infty} \frac{k_i}{n_i} = \mathcal{R} > 0$

Problem Statement

How weak the constituent codes \mathcal{C}_A and \mathcal{C}_B could be such that the overall expander code will be asymptotically good?

Asymptotic Goodness – Some Answers

The bound on the minimum distance:

$$\delta \geq \frac{\delta_A \delta_B - \gamma_G \sqrt{\delta_A \delta_B}}{1 - \gamma_G}$$

Asymptotic Goodness – Some Answers

The bound on the minimum distance:

$$\delta \geq \frac{\delta_A \delta_B - \gamma_G \sqrt{\delta_A \delta_B}}{1 - \gamma_G}$$

yields the sufficient condition

$$\sqrt{d_A d_B} > \gamma_G \Delta = \lambda_G$$

Asymptotic Goodness – Some Answers

The bound on the minimum distance:

$$\delta \geq \frac{\delta_A \delta_B - \gamma_G \sqrt{\delta_A \delta_B}}{1 - \gamma_G}$$

yields the sufficient condition

$$\sqrt{d_A d_B} > \gamma_G \Delta = \lambda_G \geq 2\sqrt{\Delta - 1}.$$

Asymptotic Goodness – Some Answers (cont.)

[Sipser Spielman '96]

- ▶ Codes \mathcal{C}_A with $d_A = \Delta$ and \mathcal{C}_B with $d_B = 2$.

Asymptotic Goodness – Some Answers (cont.)

[Sipser Spielman '96]

- ▶ Codes \mathcal{C}_A with $d_A = \Delta$ and \mathcal{C}_B with $d_B = 2$.
- ▶ Bipartite (α, ζ) -expander graph with $\zeta \geq 3/4$.

Asymptotic Goodness – Some Answers (cont.)

[Sipser Spielman '96]

- ▶ Codes \mathcal{C}_A with $d_A = \Delta$ and \mathcal{C}_B with $d_B = 2$.
- ▶ Bipartite (α, ζ) -expander graph with $\zeta \geq 3/4$.
- ▶ \Rightarrow Relative minimum distance is at least α .

Asymptotic Goodness – Some Answers (cont.)

[Sipser Spielman '96]

- ▶ Codes \mathcal{C}_A with $d_A = \Delta$ and \mathcal{C}_B with $d_B = 2$.
- ▶ Bipartite (α, ζ) -expander graph with $\zeta \geq 3/4$.
- ▶ \Rightarrow Relative minimum distance is at least α .

[Barg Zémor '04]

- ▶ Codes \mathcal{C}_A with $d_A \geq 3$ and \mathcal{C}_B with $d_B \geq 3$.

Asymptotic Goodness – Some Answers (cont.)

[Sipser Spielman '96]

- ▶ Codes \mathcal{C}_A with $d_A = \Delta$ and \mathcal{C}_B with $d_B = 2$.
- ▶ Bipartite (α, ζ) -expander graph with $\zeta \geq 3/4$.
- ▶ \Rightarrow Relative minimum distance is at least α .

[Barg Zémor '04]

- ▶ Codes \mathcal{C}_A with $d_A \geq 3$ and \mathcal{C}_B with $d_B \geq 3$.
- ▶ Random bipartite graph.

Asymptotic Goodness – Some Answers (cont.)

[Sipser Spielman '96]

- ▶ Codes \mathcal{C}_A with $d_A = \Delta$ and \mathcal{C}_B with $d_B = 2$.
- ▶ Bipartite (α, ζ) -expander graph with $\zeta \geq 3/4$.
- ▶ \Rightarrow Relative minimum distance is at least α .

[Barg Zémor '04]

- ▶ Codes \mathcal{C}_A with $d_A \geq 3$ and \mathcal{C}_B with $d_B \geq 3$.
- ▶ Random bipartite graph.
- ▶ \Rightarrow Relative minimum distance is bounded away from zero with probability close to 1.

Constituent Codes of Minimum Distance 2

Example

Take $k = 2$, $\Delta = 3$, $n = 4$.

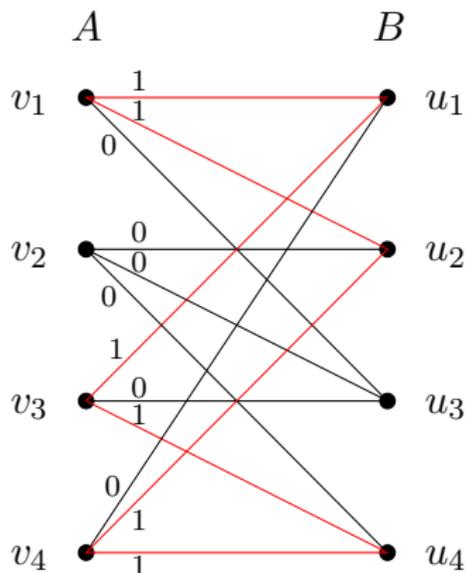
Let C_A and C_B be binary parity codes.

Constituent Codes of Minimum Distance 2

Example

Take $k = 2$, $\Delta = 3$, $n = 4$.

Let C_A and C_B be binary parity codes.



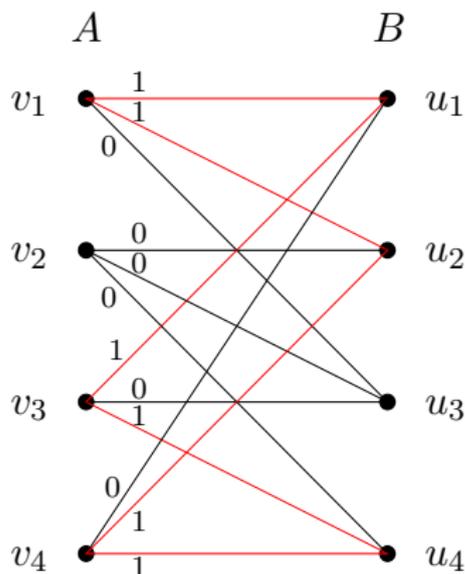
Constituent Codes of Minimum Distance 2

Example

Take $k = 2$, $\Delta = 3$, $n = 4$.

Let C_A and C_B be binary parity codes.

- ▶ Every non-zero pattern contains a cycle.



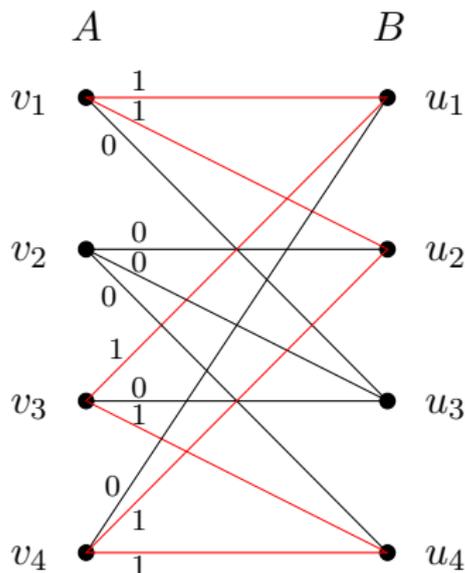
Constituent Codes of Minimum Distance 2

Example

Take $k = 2$, $\Delta = 3$, $n = 4$.

Let C_A and C_B be binary parity codes.

- ▶ Every non-zero pattern contains a cycle.
- ▶ Every cycle can be converted into a legal non-zero pattern.



Constituent Codes of Minimum Distance 2 (cont.)

Theorem

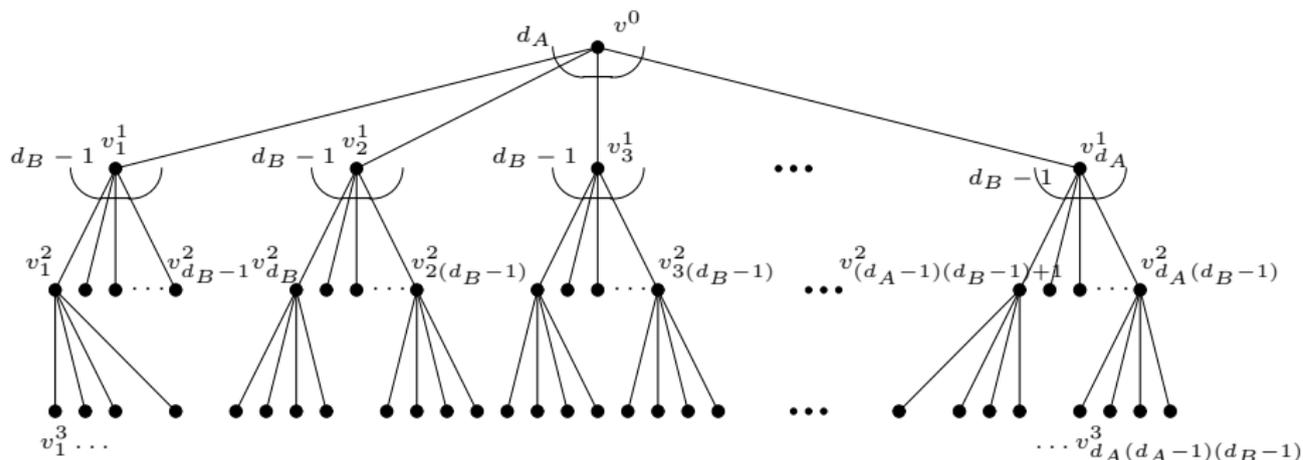
Let \mathcal{C}_A and \mathcal{C}_B be codes of minimum distance 2, and let \mathcal{G} be any Δ -regular bipartite graph. Then, the minimum distance of such code \mathbb{C} is bounded from above by

$$D \leq O(\log_{\Delta-1}(n)) .$$

Moreover, if the underlying graph \mathcal{G} is a Ramanujan graph as in [Lubotsky Philips Sarnak '88] or [Margulis '88], then the minimum distance of \mathbb{C} is bounded from below by

$$D \geq \frac{4}{3} \log_{\Delta-1}(2n) .$$

Tree-Based Lower Bound



Tree-Based Lower Bound (cont.)

Theorem

Consider the code \mathbb{C} with the constituent codes \mathcal{C}_A and \mathcal{C}_B of minimum distance $d_A \geq 2$ and $d_B \geq 2$, respectively, with the underlying graph \mathcal{G} as in [Lubotsky Philips Sarnak '88] or [Margulis '88]. Then, its relative minimum distance is bounded from below by

$$D \geq (2n)^{1/3 \cdot \log_{\Delta-1}(d_A-1)(d_B-1)} - 1.$$

Sufficient Condition

Theorem

Let \mathcal{C}_A and $\mathcal{C}_B(u)$ (for every $u \in B$) be linear codes with the minimum distance $d_A = \delta_A \Delta$ and d_B , respectively. Let \mathcal{G} be a bipartite (α, ζ) -expander such that the degree of every $u \in A$ is Δ . If

$$\frac{\delta_A}{\zeta + \delta_A - 1} < d_B ,$$

then the relative minimum distance of \mathbb{C} is $\geq \alpha \delta_A$.

Improvement over the Known Results

Example

- ▶ Ramanujan graph with $\zeta \approx \frac{1}{2}$.

Improvement over the Known Results

Example

- ▶ Ramanujan graph with $\zeta \approx \frac{1}{2}$.
- ▶ Code \mathcal{C}_A with $\delta_A = 1$ and code $\mathcal{C}_B(u)$ with $d_B = 3$.

Improvement over the Known Results

Example

- ▶ Ramanujan graph with $\zeta \approx \frac{1}{2}$.
- ▶ Code \mathcal{C}_A with $\delta_A = 1$ and code $\mathcal{C}_B(u)$ with $d_B = 3$.
- ▶ Then,

$$\frac{\delta_A}{\zeta + \delta_A - 1} < d_B .$$

Improvement over the Known Results

Example

- ▶ Ramanujan graph with $\zeta \approx \frac{1}{2}$.
- ▶ Code \mathcal{C}_A with $\delta_A = 1$ and code $\mathcal{C}_B(u)$ with $d_B = 3$.
- ▶ Then,

$$\frac{\delta_A}{\zeta + \delta_A - 1} < d_B .$$

- ▶ \Rightarrow Relative minimum distance of \mathbb{C} is $\geq \alpha\delta_A$.

Improvement over the Known Results

Example

- ▶ Ramanujan graph with $\zeta \approx \frac{1}{2}$.
- ▶ Code \mathcal{C}_A with $\delta_A = 1$ and code $\mathcal{C}_B(u)$ with $d_B = 3$.
- ▶ Then,

$$\frac{\delta_A}{\zeta + \delta_A - 1} < d_B .$$

- ▶ \Rightarrow Relative minimum distance of \mathbb{C} is $\geq \alpha\delta_A$.
- ▶ The previously-known bound does not lead to any interesting result.

Further Research

- ▶ We showed necessary and sufficient condition for asymptotic goodness of expander codes.

Further Research

- ▶ We showed necessary and sufficient condition for asymptotic goodness of expander codes.
- ▶ We presented new bounds on the minimum distance of expander codes.

Further Research

- ▶ We showed necessary and sufficient condition for asymptotic goodness of expander codes.
- ▶ We presented new bounds on the minimum distance of expander codes.
- ▶ The new condition improves on the known results for a range of parameters.

Further Research

- ▶ We showed necessary and sufficient condition for asymptotic goodness of expander codes.
- ▶ We presented new bounds on the minimum distance of expander codes.
- ▶ The new condition improves on the known results for a range of parameters.
- ▶ Tight (necessary and sufficient) conditions are still remain an open problem...